An Evaluation of GIS/LIDAR Remote Sensing Methods for Historic Hydraulic Gold Mine Investigation, Grant County, Oregon

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# Management Context



Large number of historic mining features

Incomplete documentation during timber harvest era

New management paradigm- landscape scale restoration harvest

# What is lidar?

Remote sensing technique using airborne lasers and GPS to capture three dimensional data points for the earth's surface

- Each laser pulse results in multiple "returns" of laser light reflected back to sensors in the plane
- The first return captures the highest point in the vegetation, the second return limbs on trees or understory vegetation, the last return ideally captures the surface of the ground
- The resultant "data cloud" can be processed to generate a variety of landscape models

# What is lidar?

Raster model with heights differentiated by color- good for vegetation modeling

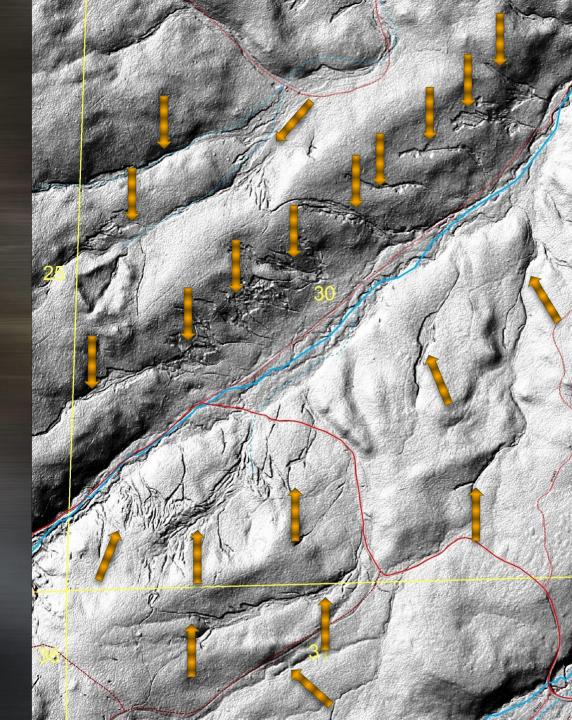
Modeling only the last returns provides a fairly accurate representation of the ground surface

 Areal photo showing a tributary of the Middle Fork John Day River



Bare Earth
 Model of same
 area based on
 lidar last returns

Deeply incised features are all remnants of historic placer mining



#### LIDAR Remote-Sensing Inventory and Evaluation (Warm Springs Geo Visions)

Inventory- Identify and map hydraulic mining features within 30,720-acre study area

Evaluation- Assess suitability of methods and data output for future inventory projects

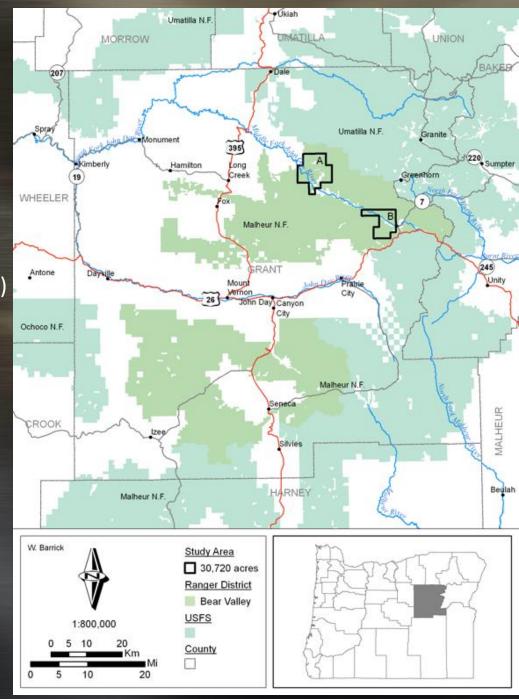
### Study Area Background

• Environment

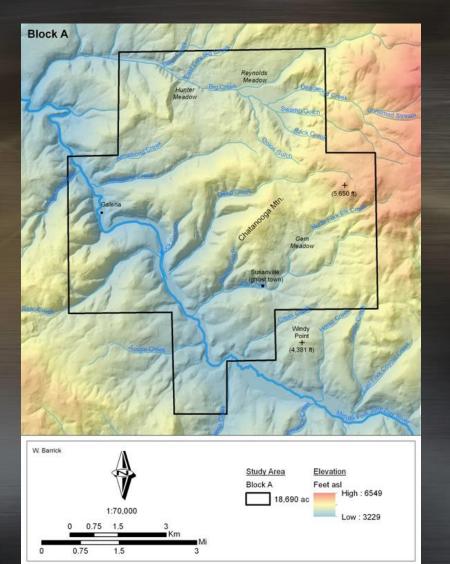
Blue Mountains (Middle Fork John Day R.) Numerous active streams Abundant winter snow melt Gold-bearing geology Dense coniferous forest

Culture History

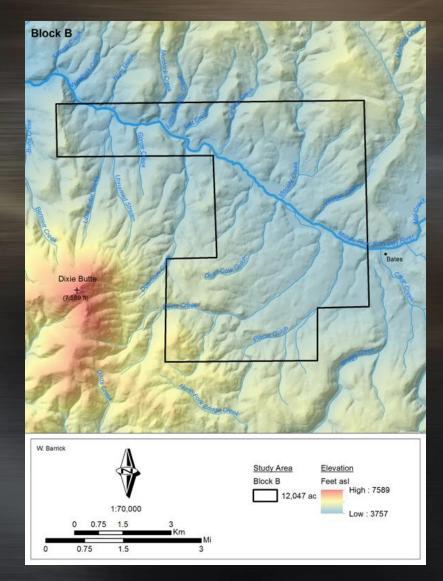
Precontact: Plateau and Great Basin Euro-American and Chinese miners Susanville Gold Mining District (ca. 1864)



### Block A: 18,680 acres



### Block B: 12,047 acres



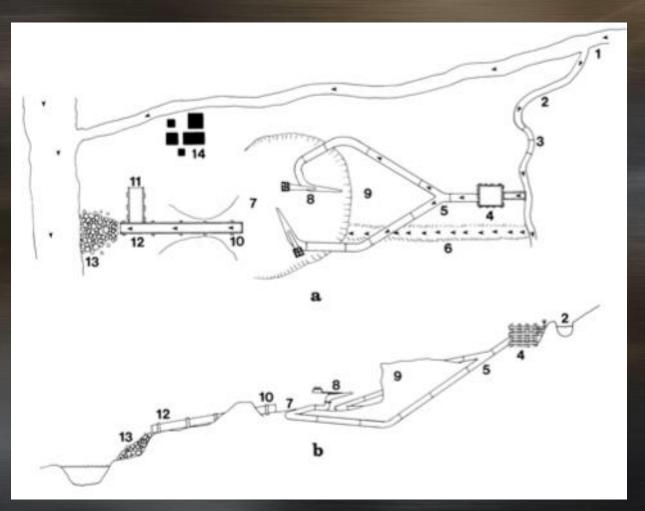
### Hydraulic Gold Mining (placer mining)



-Pressurized water is used to undermine and wash away gold-bearing alluvial sediments (placer deposits) into sluicing systems that concentrate the sediments and collect gold particles

#### **Mining System Features**

- Prospect pits
- Reservoir
- Wing dam
- Ditch intake (#1)
- Lateral ditch (#2)
- Wash pit (#8)
- Sluice channel (#7)
- Tailings (#13)
- Camp (#14)



#### (LaLand 1985:38)

#### LIDAR Analysis Methods/Materials

#### **Remote Sensing Inventory**

- LIDAR elevation data
- Geographic Information Systems (GIS)
- Surface anomaly recognition technique

Field Investigation/Evaluation

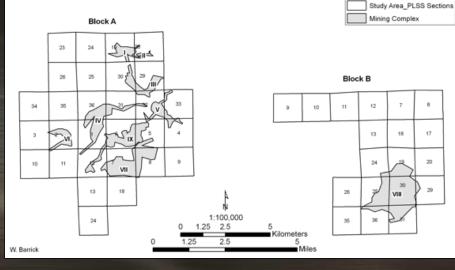
Ground truthing (28% sample)
 Thematic accuracy- correct feature type identified
 Spatial precision- mapped features are within 1 m of actual location
 Completeness- proportion of mapped features compared to total

#### **Results: Remote Sensing**

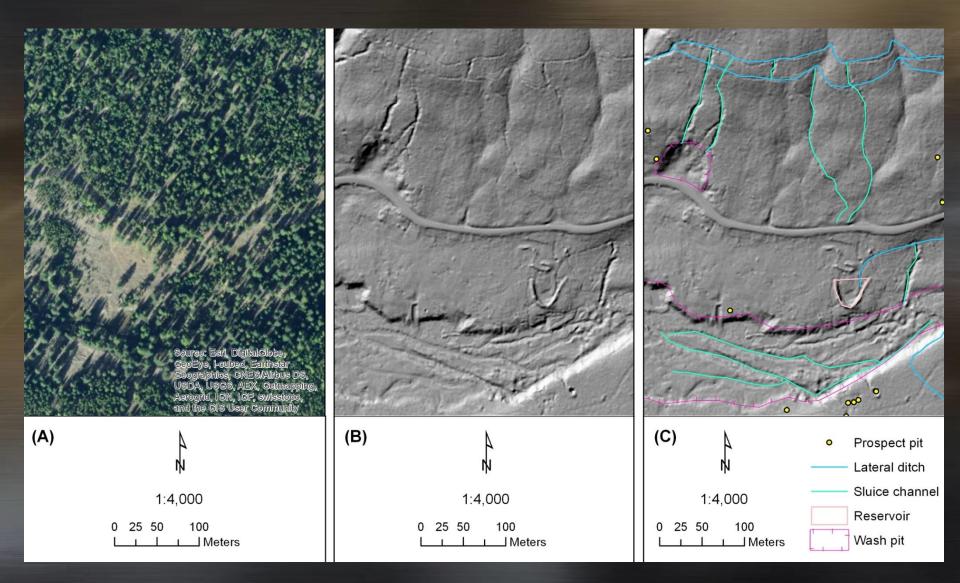
• 687 hydro-mining features

#### • 9 hydro-mining complex

Hydraulic Mining Complex	Area (acres)	Associated Previous Documentation	Mapped Features (count)										
			Prospect Pit	Reservoir	Wing Dam	Lateral Ditch Intake	Lateral Ditch	Wash Pit	Sluice Channel	Tailings	Camp/ Cabin	Total	
I	176	Y	43	1	1	3	7	3	12	1	2	73	
п	28		9			1	2	4	1	0		17	
ш	280		8			1	11	8	6	6		40	w
IV	483		31			3	5	7	13	1	1	61	
v	251		17			3	8	6	16	3		53	
VI	163		27		1	3	17	10	15	10		83	
VII	721	Y	69			3	11	9	7	2	1	102	
VIII	1,431	Y	31	2	2	7	43	30	28	30	2	175	
IX	512		75			1	2	1	2	0		81	
None											2	2	
Total	4,045	3	310	3	4	25	106	78	100	53	8	687	



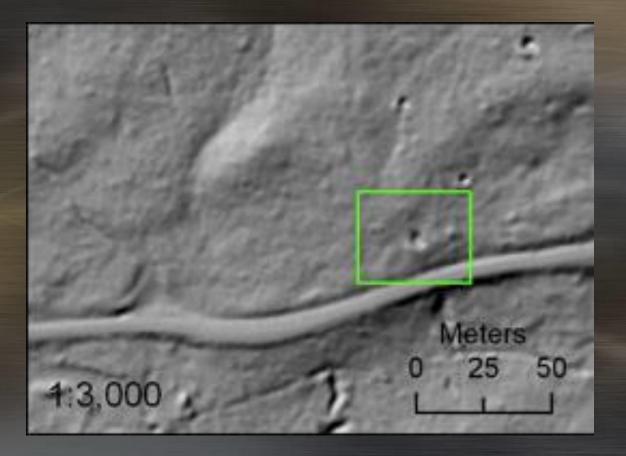
#### **Discussion: Vegetation Penetration**



View of vegetation canopy (A), LIDAR bare-earth model (B), and feature mapping (C)



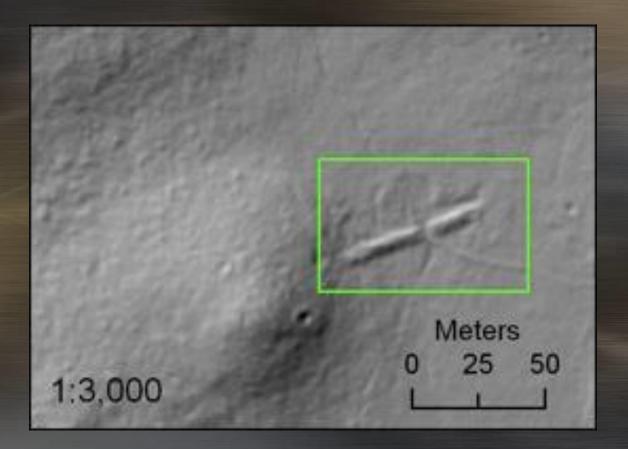
#### **Prospect Pit**



**Prospect Pit** 



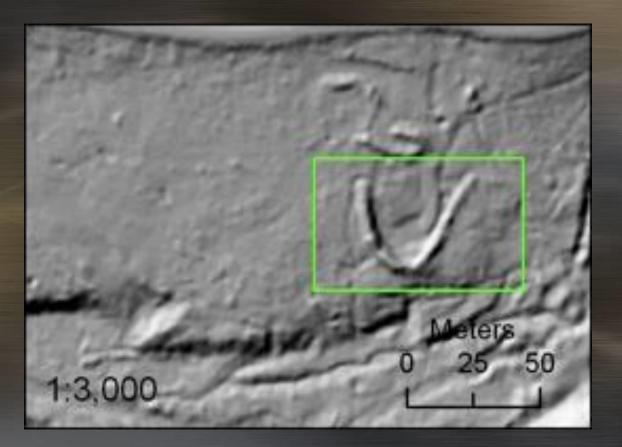
Wing Dam



Wing Dam



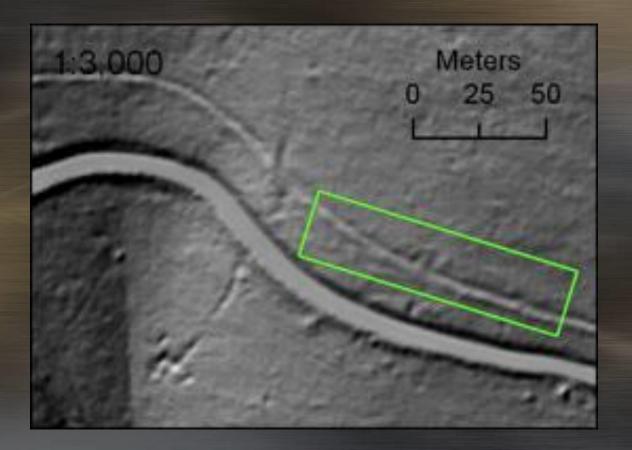
Reservoir



Reservoir



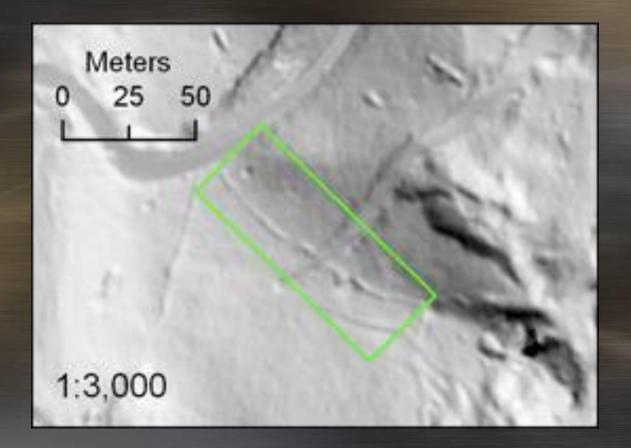
Lateral Ditch



#### Lateral Ditch



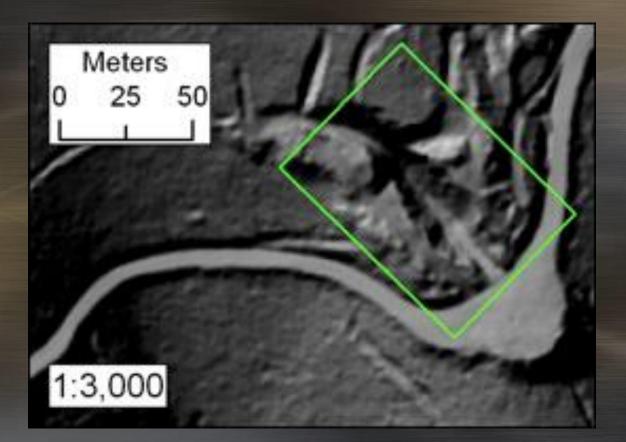
**Sluice Channel** 



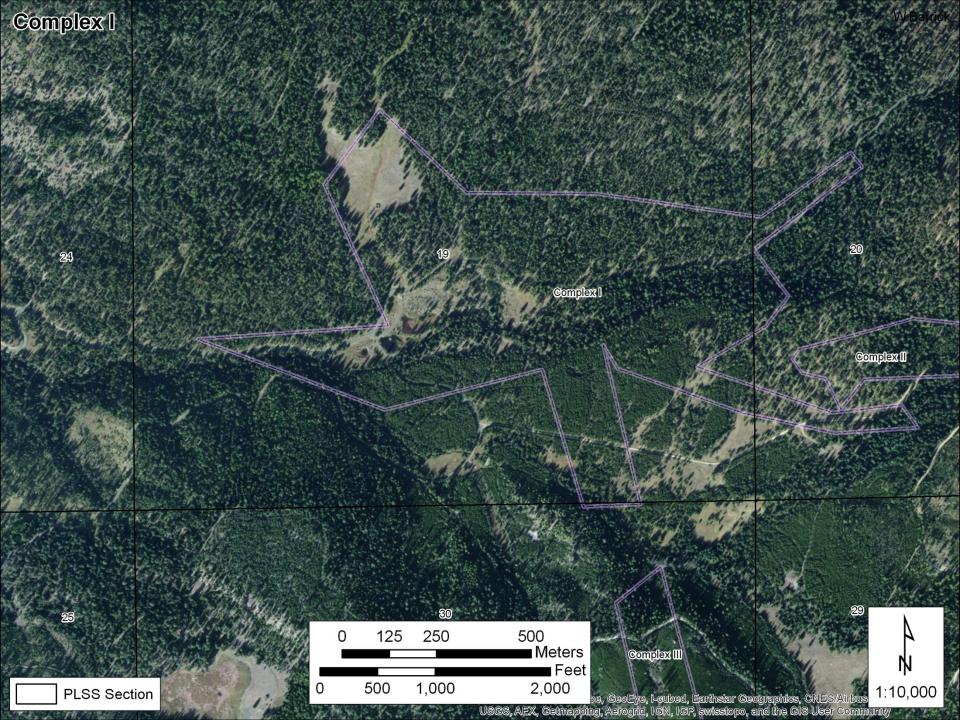
#### **Sluice Channel**

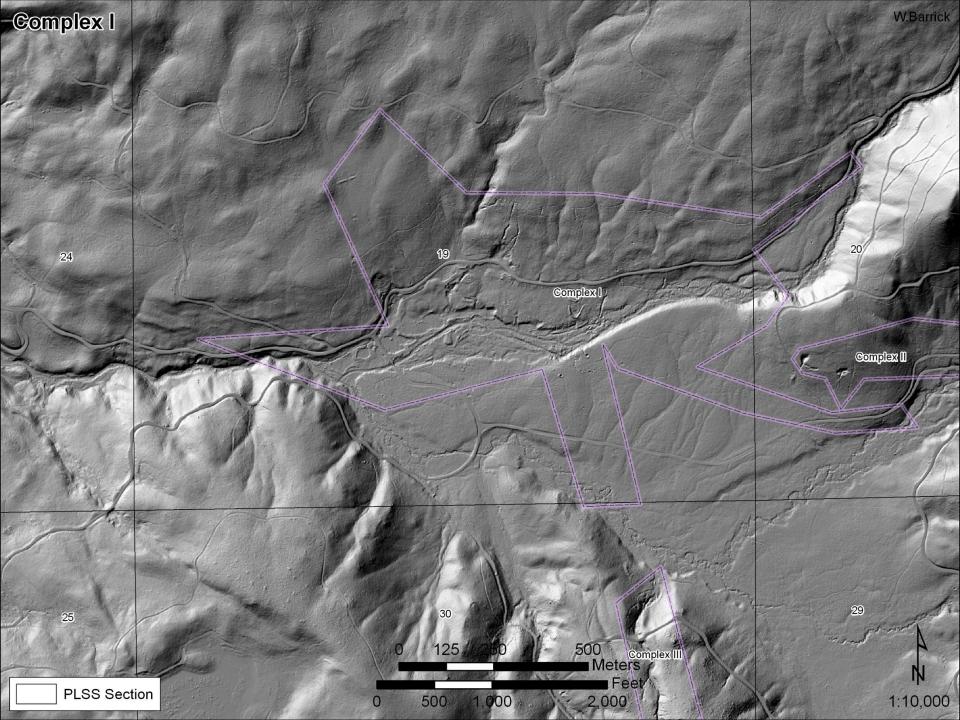


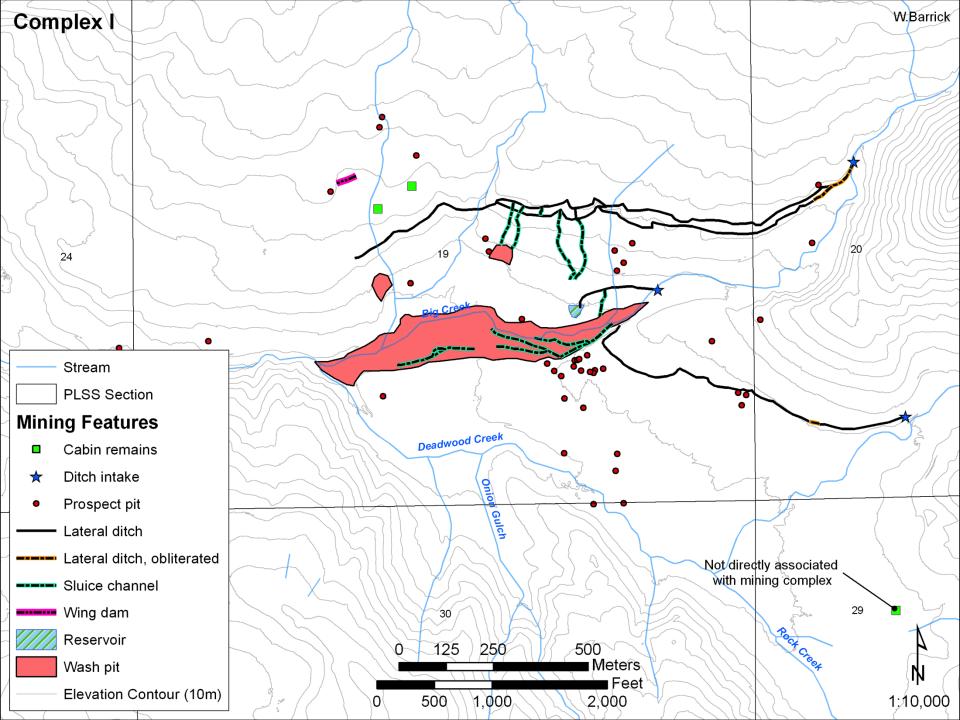
Wash Pit



Wash Pit



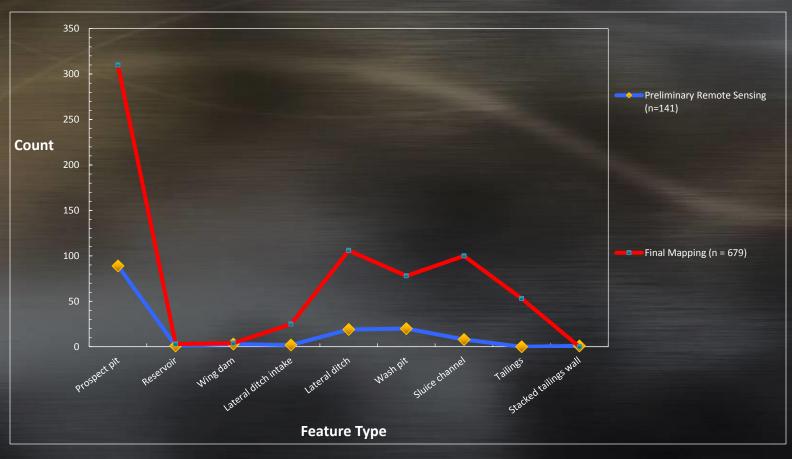




#### Field Investigation/Evaluation

#### Feature Verification Study

- Remote Sensing (before ground truthing)
  - *Thematically accuracy* correct feature type identified (78%)
  - Spatially precise- digitally mapped features are within 1 m of actual location (90%)



#### ★ 79% increase in identified features after ground truthing

# Conclusion

#### Strengths

- Effective vegetation-penetrating feature identification/mapping capabilities
- Cost and time-effective inventory within expansive study areas
- Ability to produce high-quality data outputs

#### Limitations

- Need for ground-truth field investigations
- Need for previous site-level documentation
- Difficulty/inability to remotely detect some feature types (e.g. tailings, stacked rock walls, and cabin/domestic support structures)

#### Next Steps/Recommendations...

- 1. Stand-alone remote sensing is *not* recommended for comprehensive inventory-scale studies
  - Field investigations should be applied after remote sensing (repeated if necessary)
- 2. Landscape-scale documentation and management
  - LIDAR mapping ideal for understanding spatial relationships

#### 1. 3-D Modeling

• Use to better understand hydraulic mining systems/ quality control for mapping

#### References

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