

Comparison of Methods for Estimating Stream Channel Gradient Using GIS

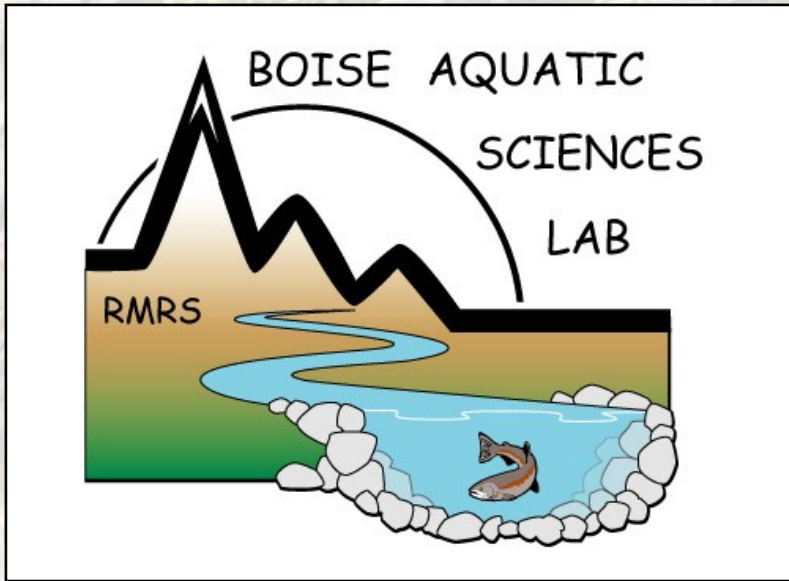
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USDA Forest Service, Rocky Mountain Research Station
Boise Aquatic Sciences Lab

Boise, ID

September 14, 2006

Special thanks to Sharon Parkes....



Stream Channel Gradient

Rate of elevation change



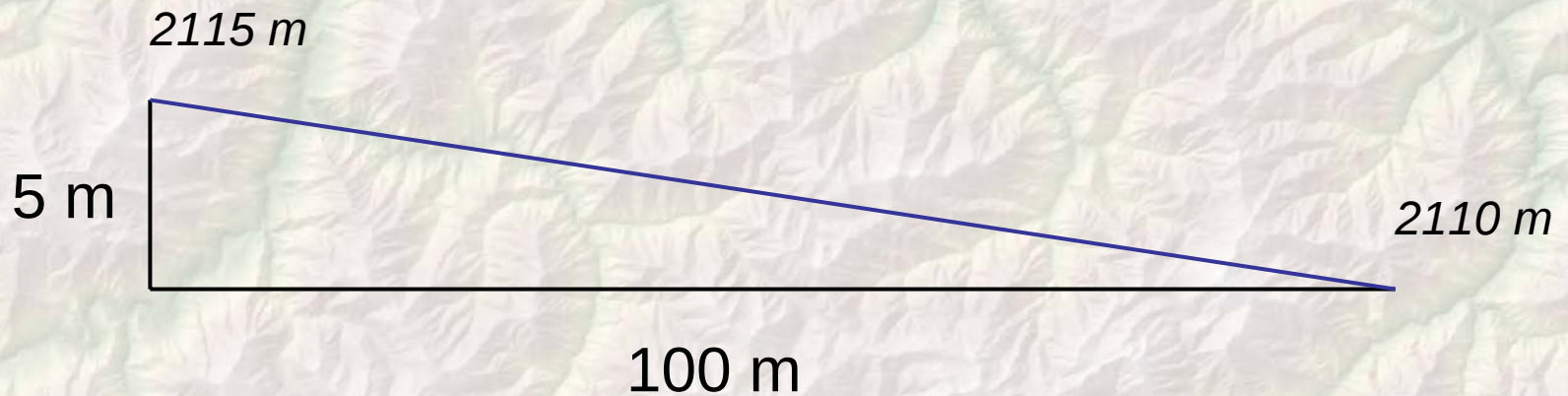
High



Low

Computing Gradient

Rise / Run = Slope



$$5 / 100 = .05 = 5\% \text{ slope}$$

Reasons for Modeling Stream Gradient

- Predictor of channel morphology



Pool-riffle

1%



Plain-bed

3 - 4%



Step-pool

10%

Reasons for Modeling Stream Gradient

- Estimate distribution of aquatic organisms

“Channel gradient and channel morphology appeared to account for the observed differences in salmonid abundance, which reflected the known preference of juvenile coho salmon [Oncorhynchus kisutch](#) for pools.”

- Hicks, Brendan J. and James D. Hall, 2003



Reasons for Modeling Stream Gradient

- Predict debris flow transport and deposition

“Transportation and deposition of material in confined channels are governed primarily by water content of debris, channel gradient, and channel width.”



- Fannin, R. J and T. P. Rollerson, 1993

Our Purpose for Modeling Stream Gradient

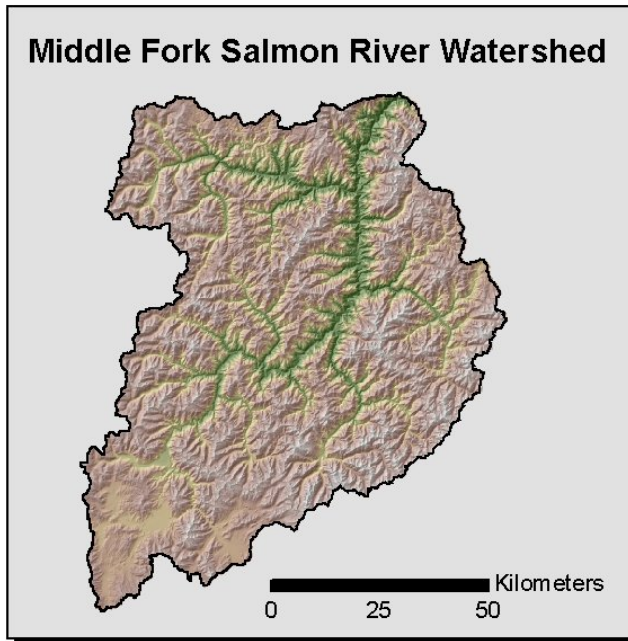
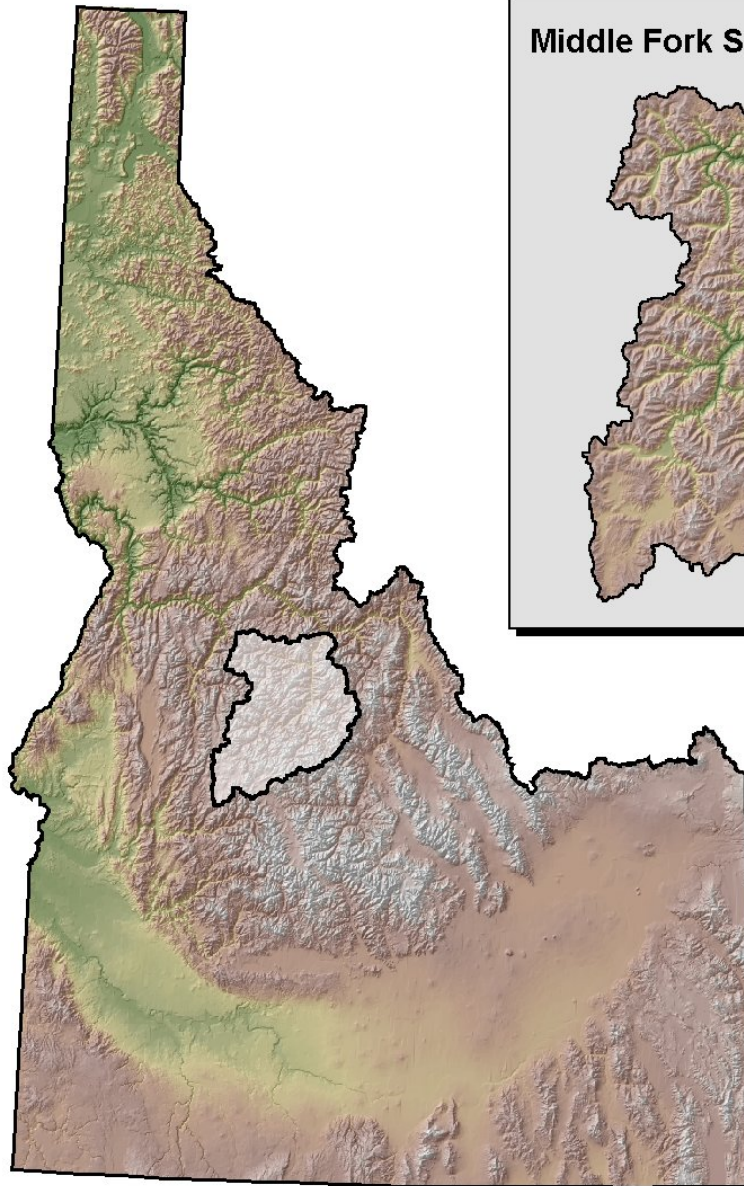
- Estimate stream bed grain size to identify salmon spawning habitat

$$\text{Grain Size} = \frac{1000 \rho g h S}{(\rho_s - \rho) g \tau^*} = \frac{1000 \rho (c A^f S)^{1-n} (a A^b)^n}{(\rho_s - \rho) k}$$

S = channel slope

Grain size 16 – 51 mm



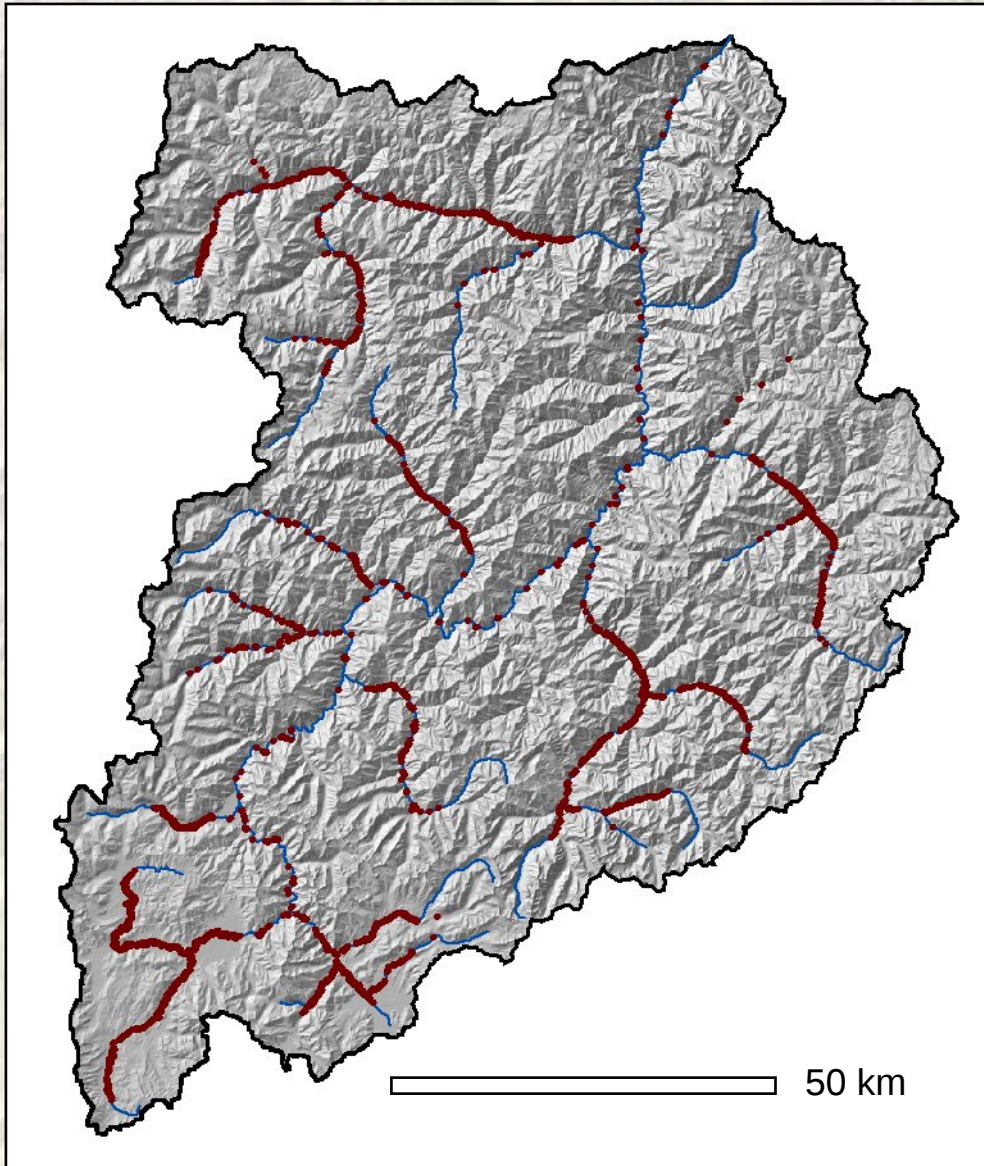


Idaho

Study Area

10,000 km
of rivers and
streams

Chinook Salmon Spawning Sites 1995 - 2004



Research questions

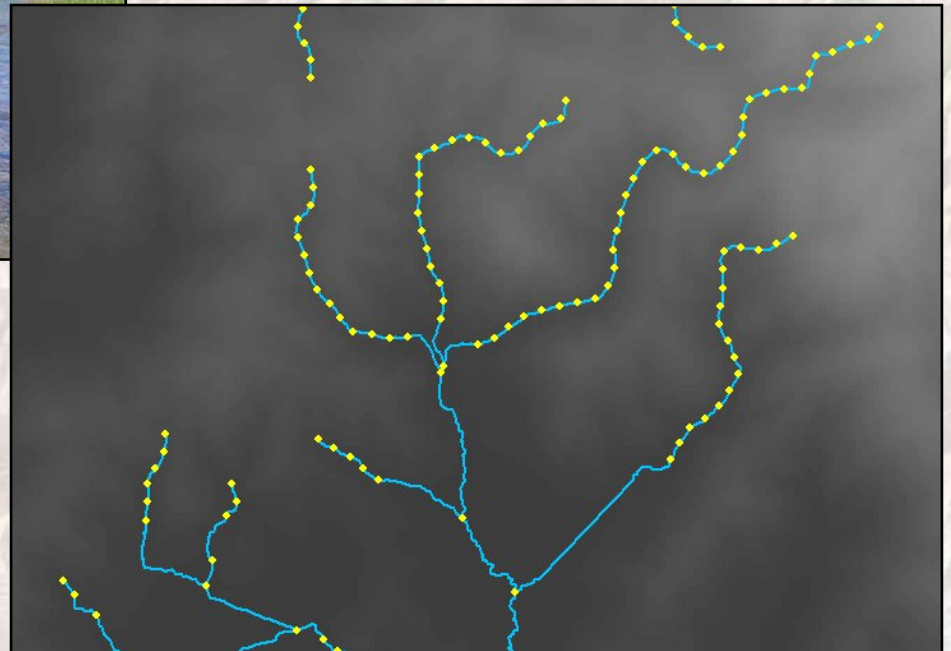
- 1) Where are the optimum spawning sites?
- 2) Where might spawning expand if populations increased to historical levels?
- 3) Can grain size prediction be applied elsewhere?

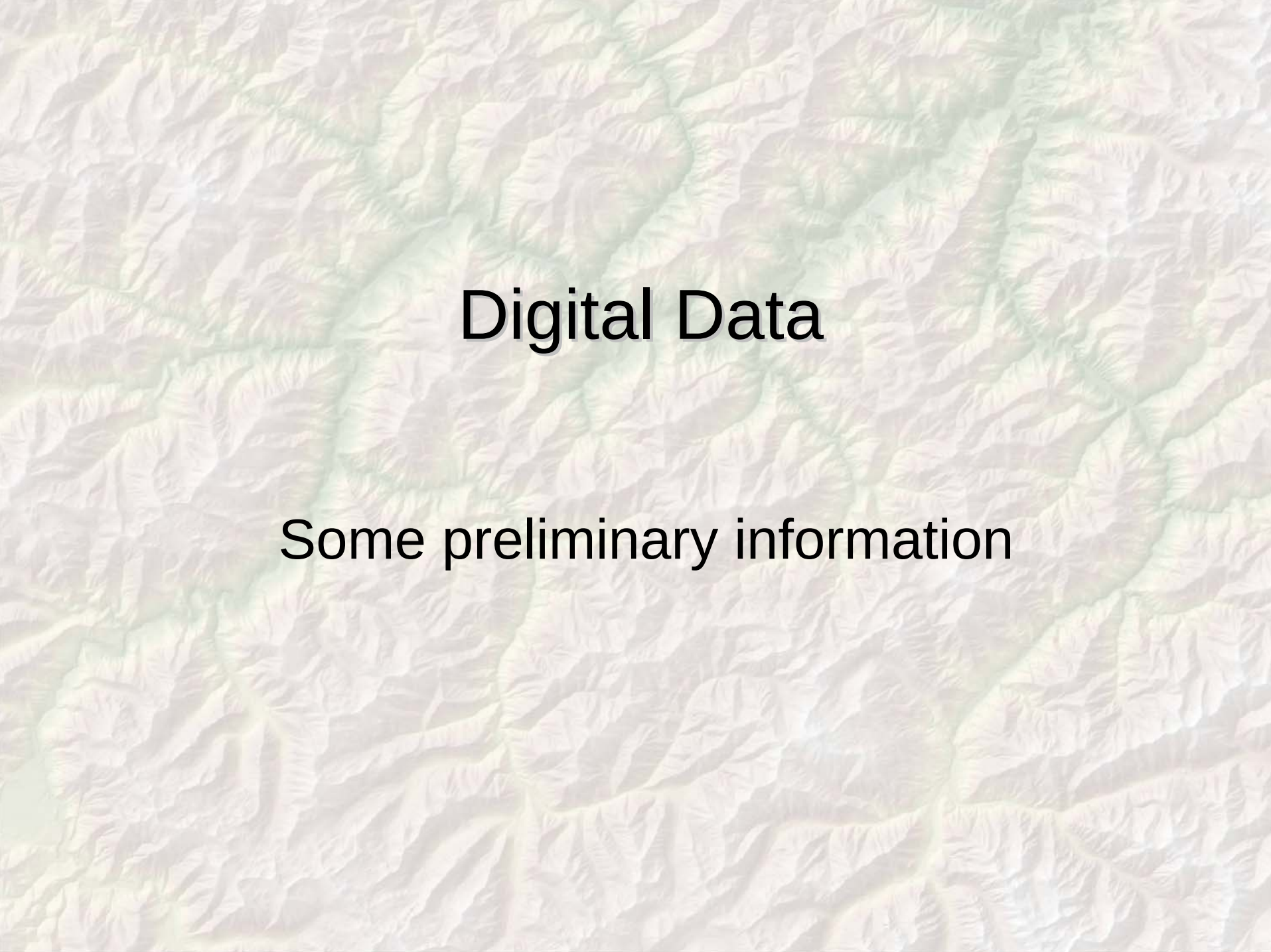
Measuring Gradient



Directly

Remotely



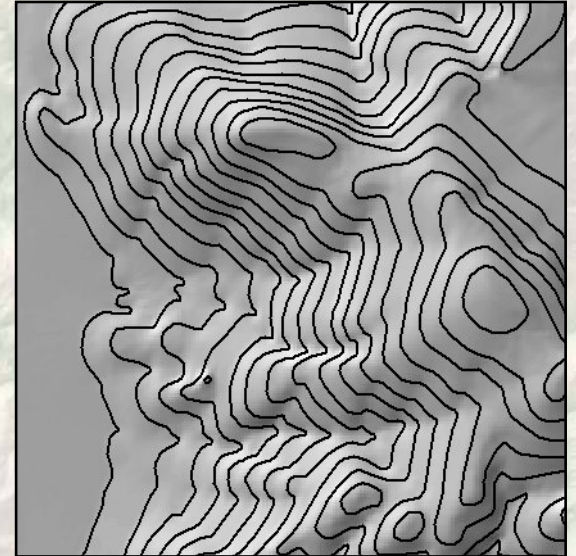


Digital Data

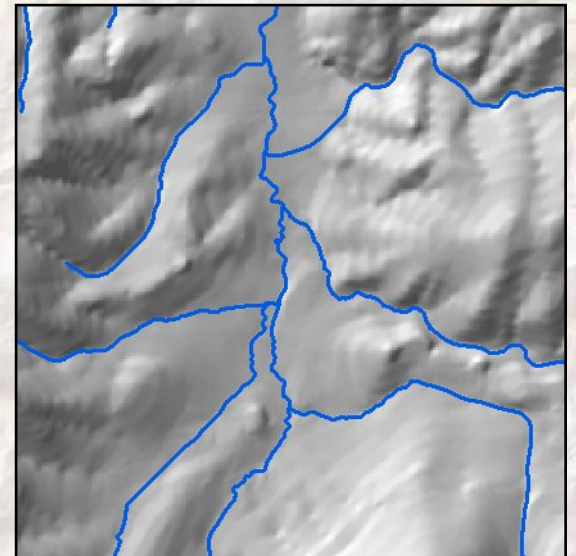
Some preliminary information

Necessary Data

1) Elevation - to compute
rise

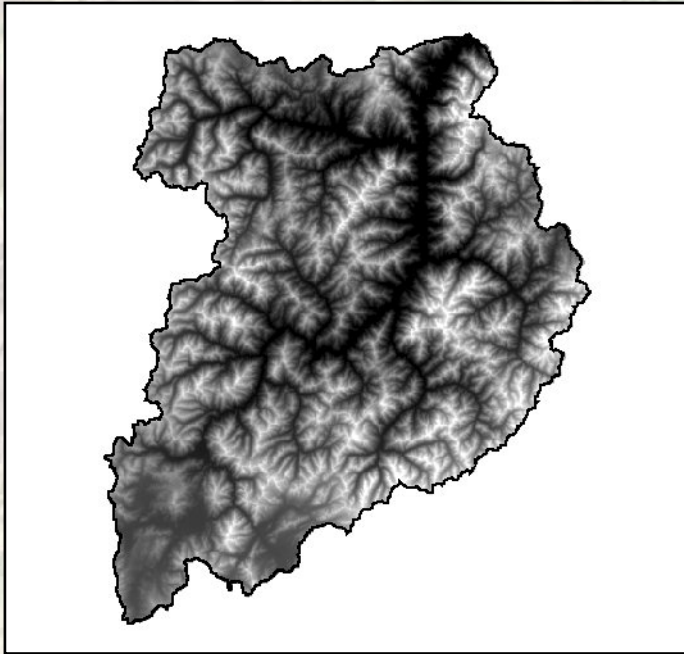


2) Stream lines - to
compute run



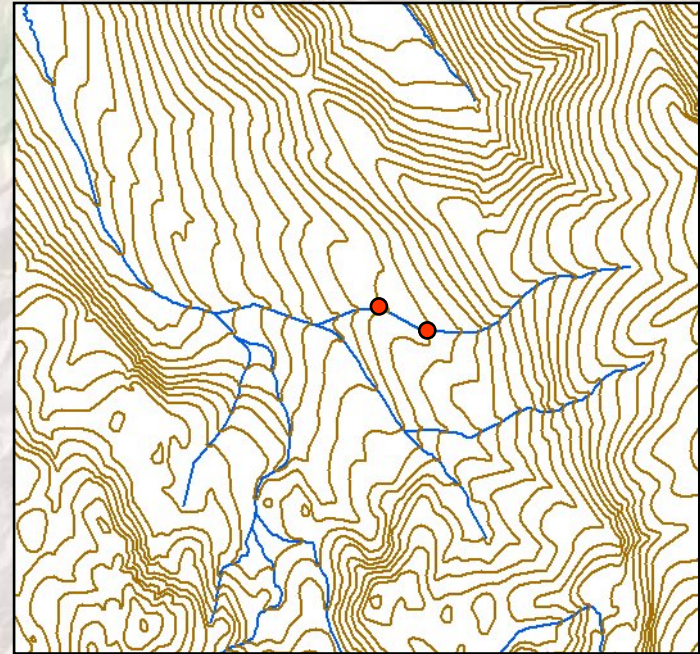
Choose Elevation Data

Digital Elevation Model
(DEM)



USGS National
Elevation Dataset
(NED)

Contour lines

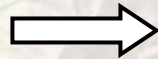


USGS 1:24,000 scale

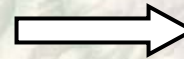
DEM Production Process



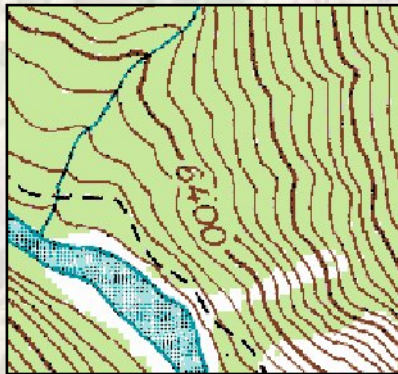
1) Aircraft



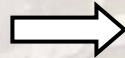
2) Aerial photo



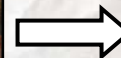
3) Stereo plotter



4) Map production

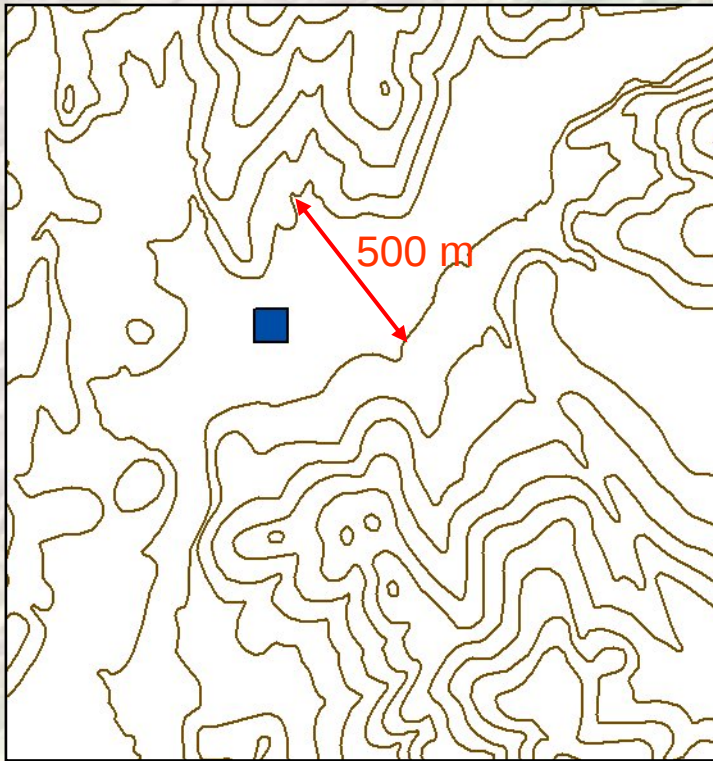


5) Scan and tag



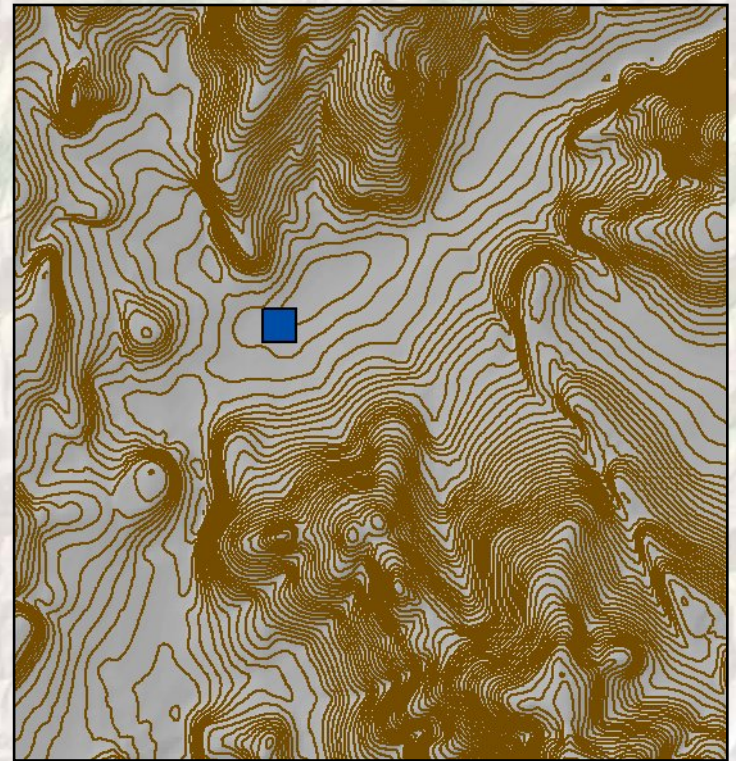
6) LT4X

Original Contours and 10 m DEM Model



Original 40' contours

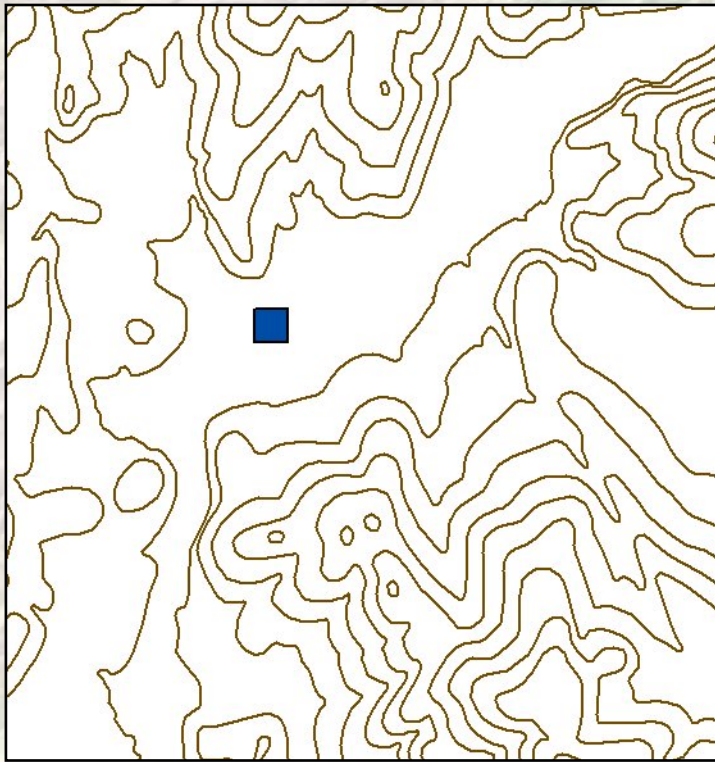
→
LT4X



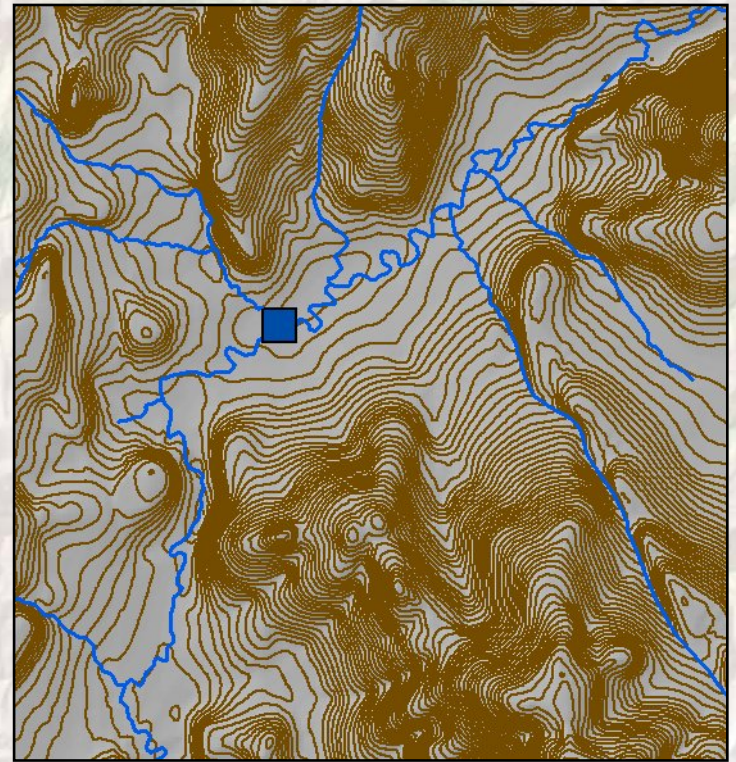
2 m contours derived
from 10 m DEM

Blue box = 100 m x 100 m

Original Contours and 10 m DEM Model

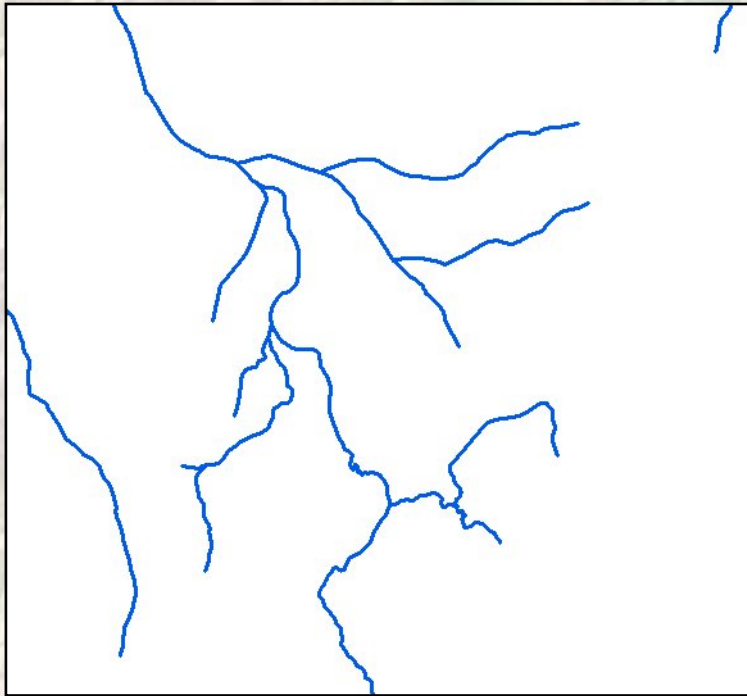


Original 40' contours

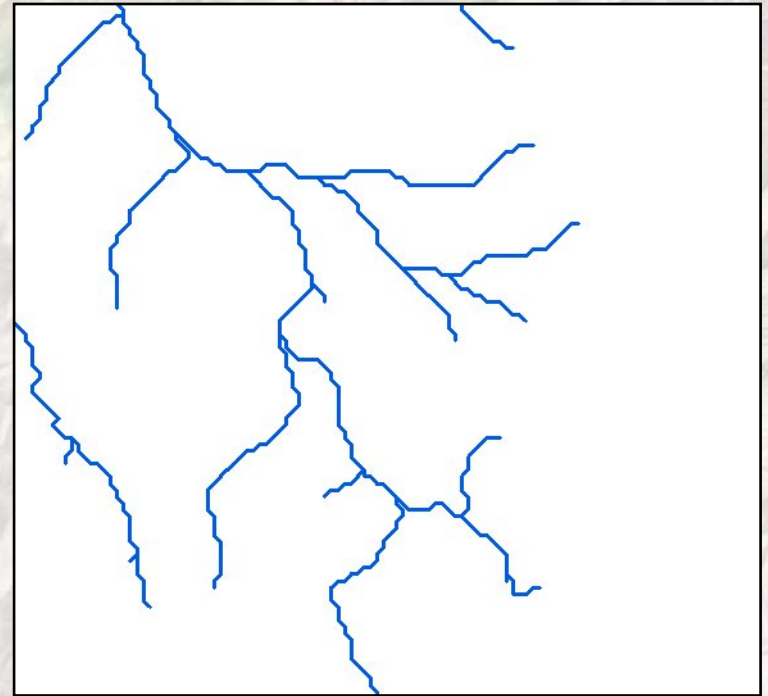


2 m contours derived
from 10 m DEM

Choose Stream Line Data

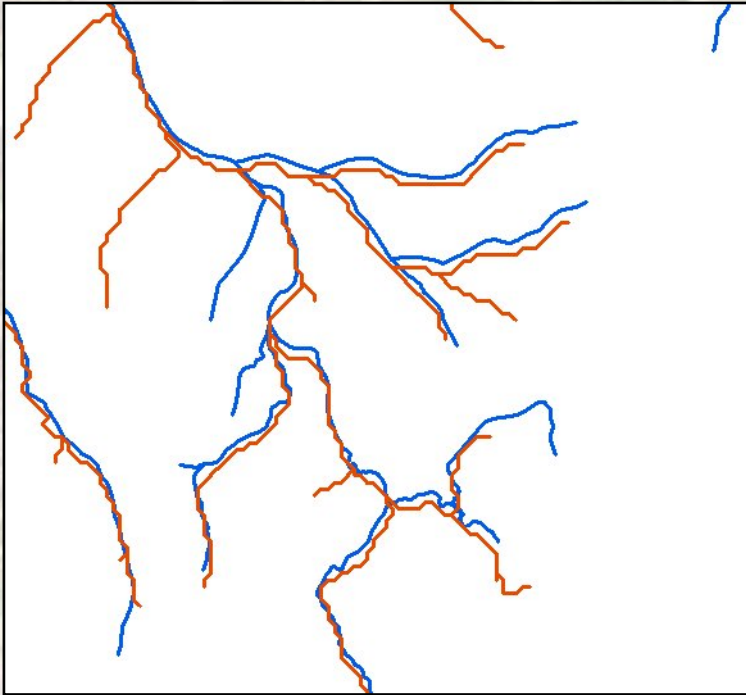


National Hydrography
Dataset (NHD)

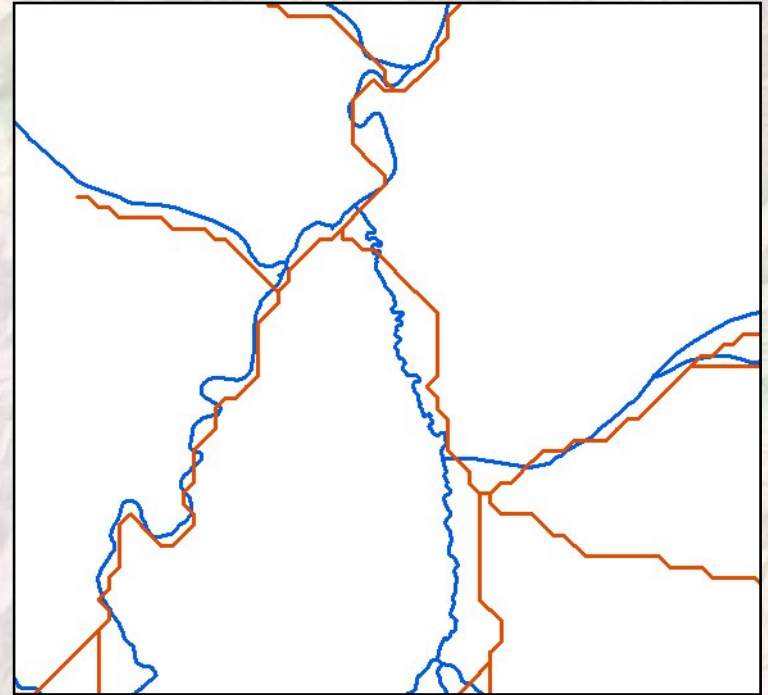


Synthetic stream lines

NHD and Synthetic Comparison

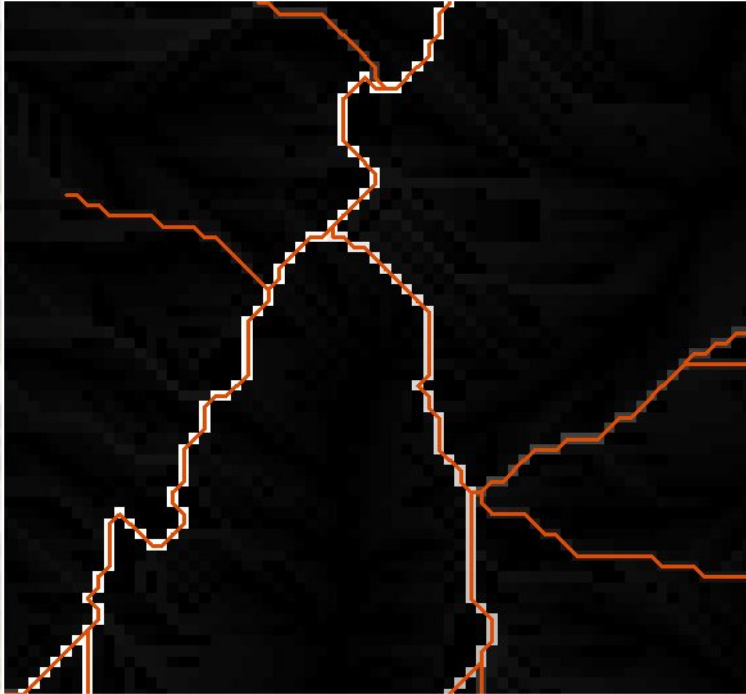


Higher gradient

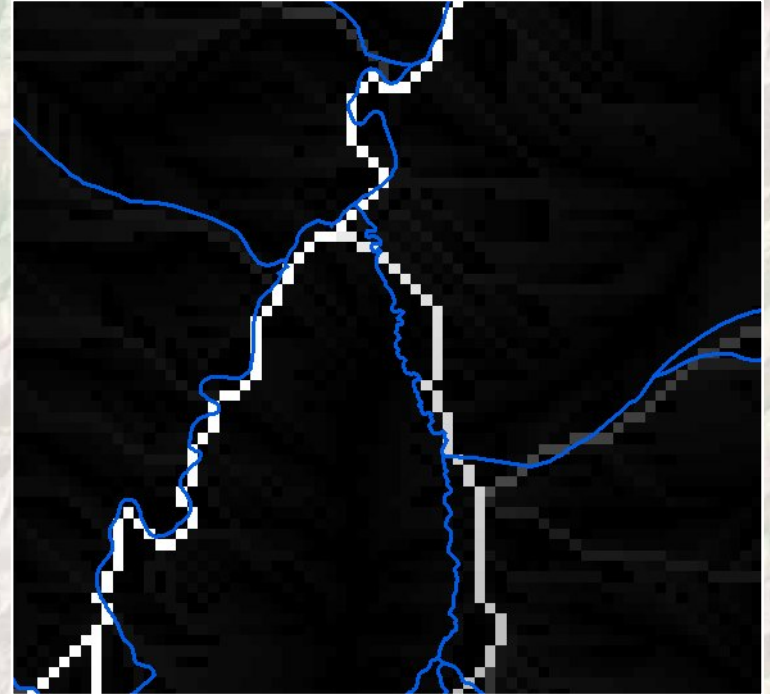


Low gradient

Synthetic Streams “Fit” the DEM



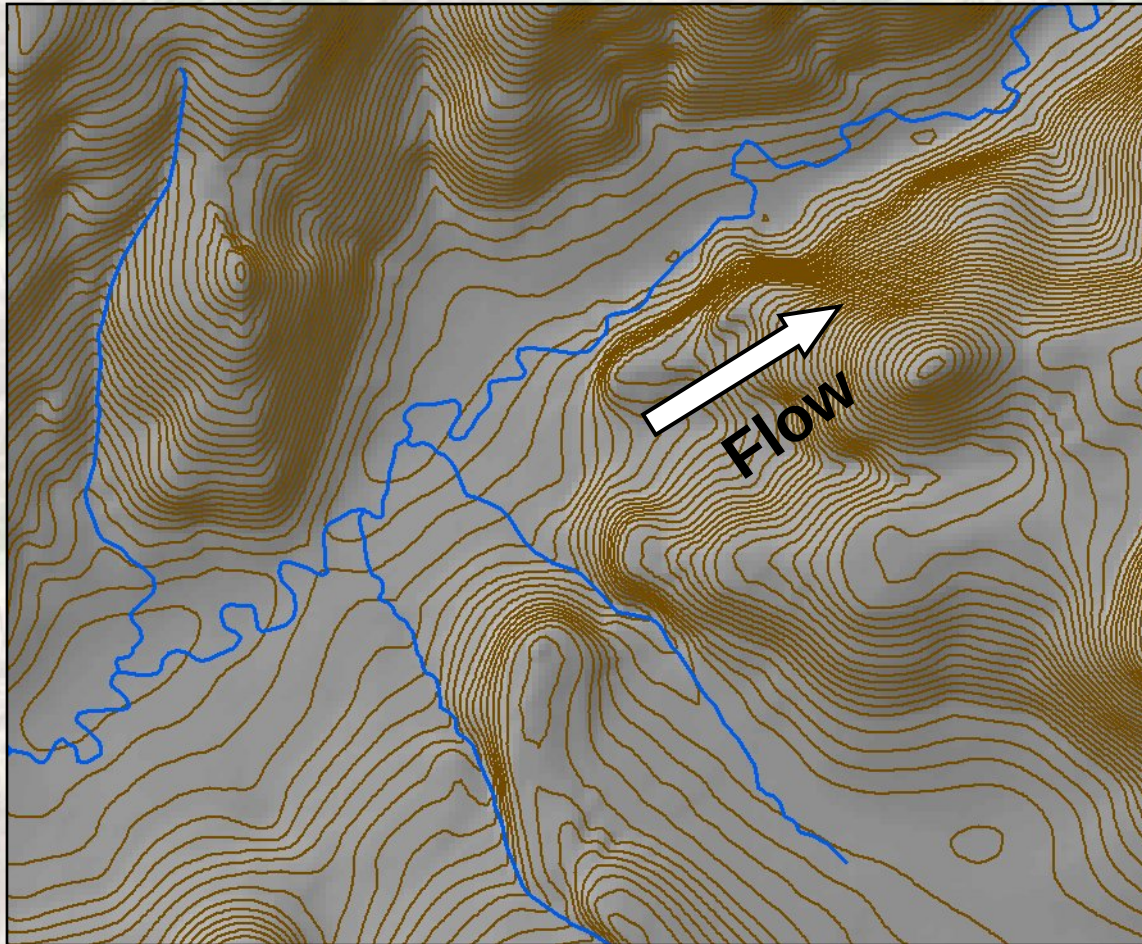
Synthetic streams follow the flow accumulation path and fall within the DEM channel



NHD streams often fall on DEM side slopes

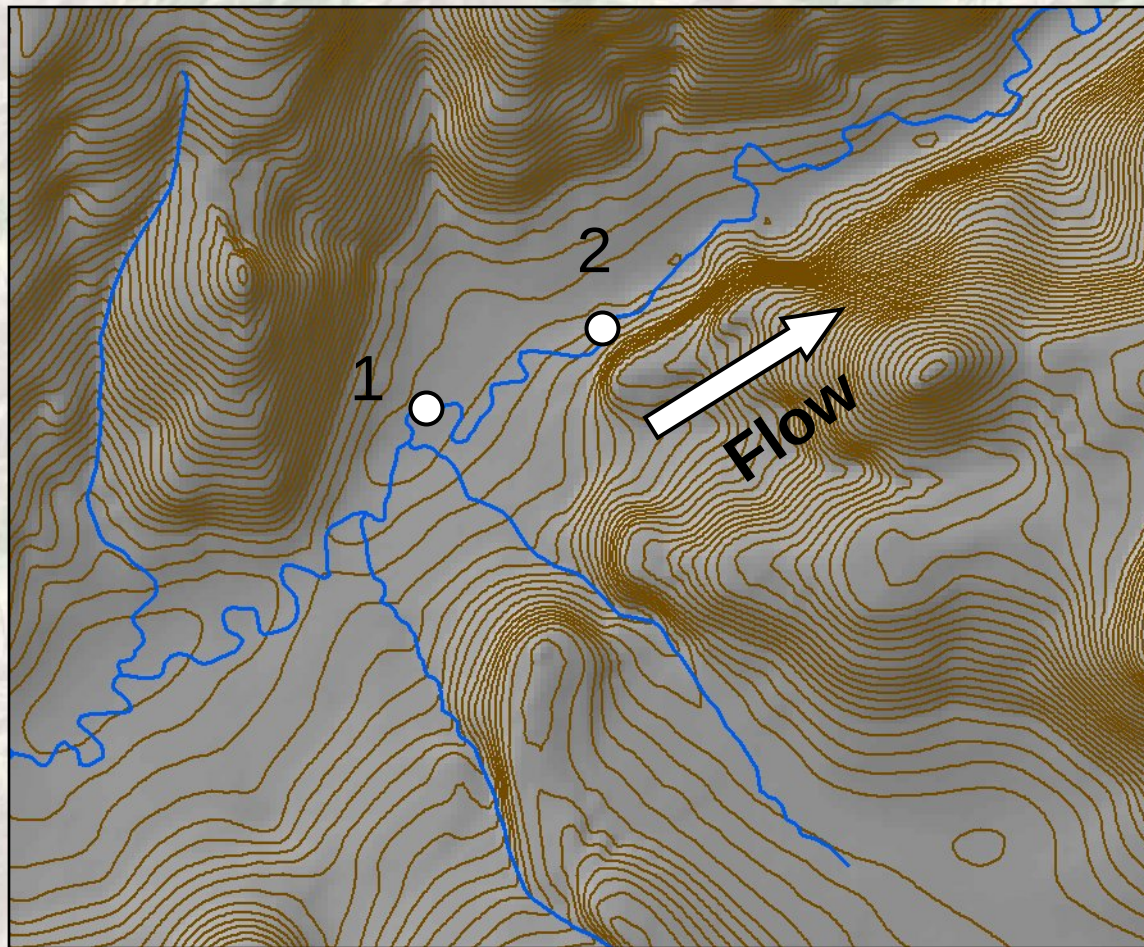
NHD and 10 m DEM Contours

2 m interval

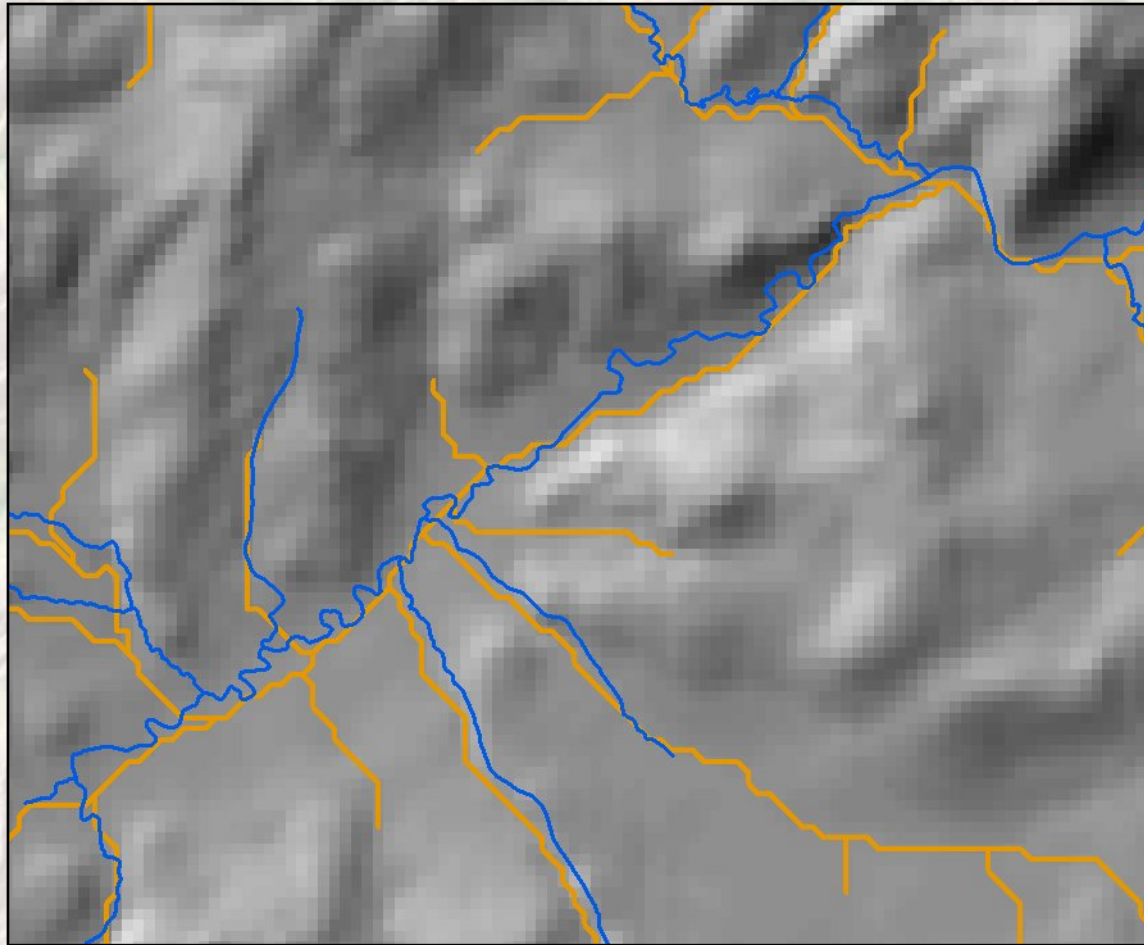


NHD and 10 m DEM Contours

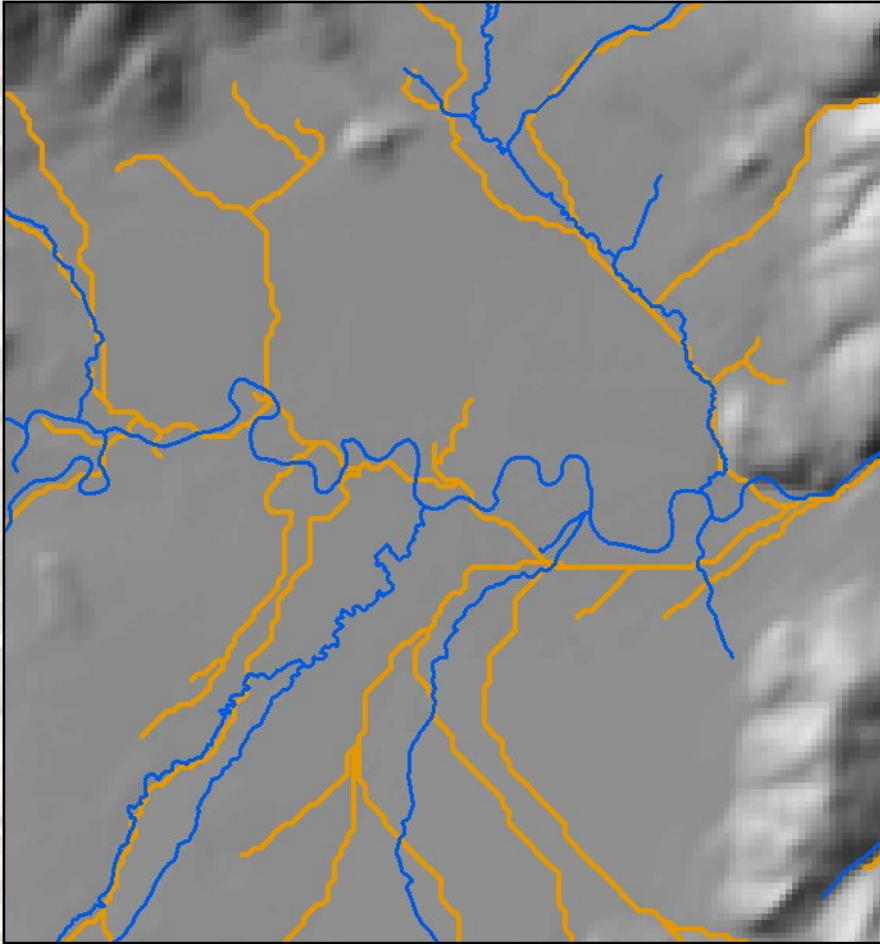
2 m interval



NHD Streams Represent Sinuosity More Accurately



Shortening with Synthetic Streams is Substantial



In low gradient areas,
synthetic streams can
underestimate stream
length by approximately
25%

5412 m vs. 4092 m

The Dilemma

Elevations along synthetic streams consistently flow down hill and represent elevation (rise) more normally

However....

Stream channel length, or sinuosity (run) is better represented by NHD stream lines

$$\text{Rise} / \text{Run} = \text{Slope}$$

Best Data Choices for Computing Stream Channel Gradient

- 1) 10 m NED DEM
- 2) NHD stream lines

Spatial Accuracy of NHD



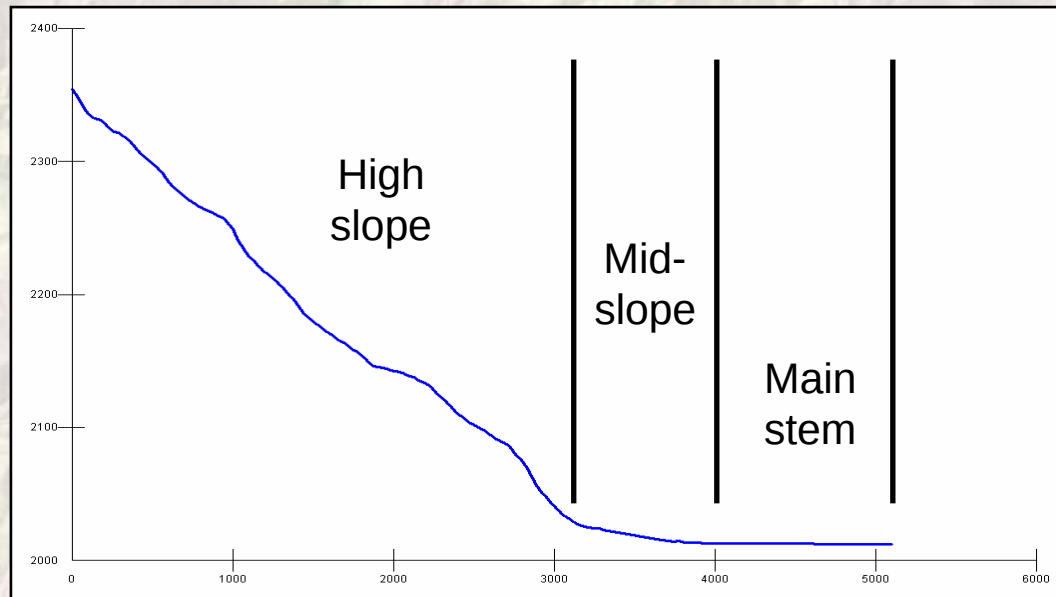
A detailed topographic map of a mountainous region, showing numerous ridges, valleys, and peaks. The map uses a color gradient where green represents lower elevations and brown/tan represents higher elevations. The terrain is rugged and complex, with many small-scale features.

Measuring Gradient

Measuring Gradient

We used three approaches dependent on gradient

- 1) High slope – 3% - 50% gradient
- 2) Mid-slope – 1.4% mean
- 3) Main stem – 1.0% or less



Stream channel
profile

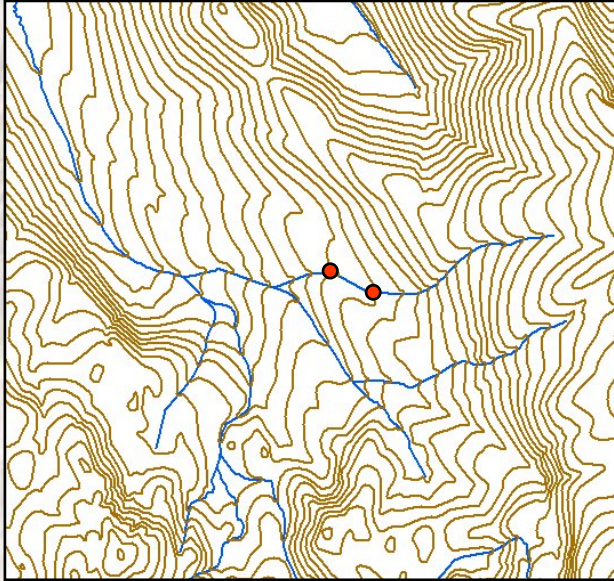
Why Use Three Approaches?

DEM accuracy changes depending
on the original quad contour spacing

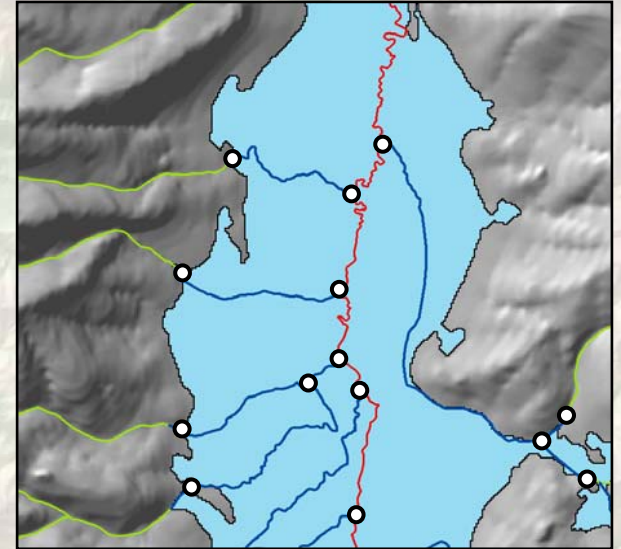
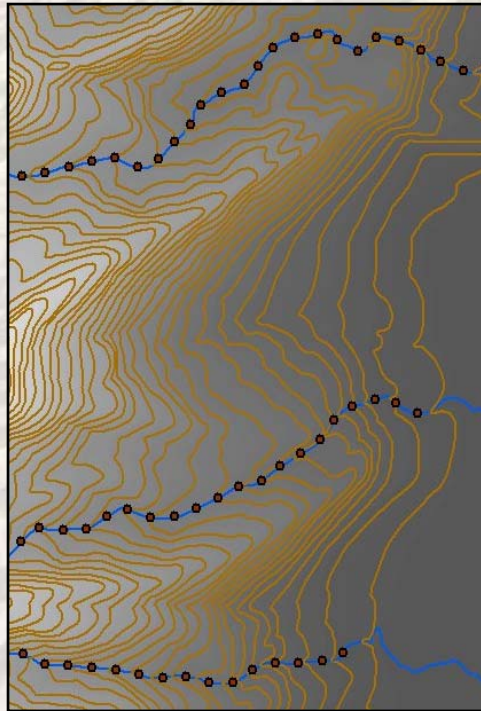
and

Landscape position

Possible Approaches



At contour
crossings

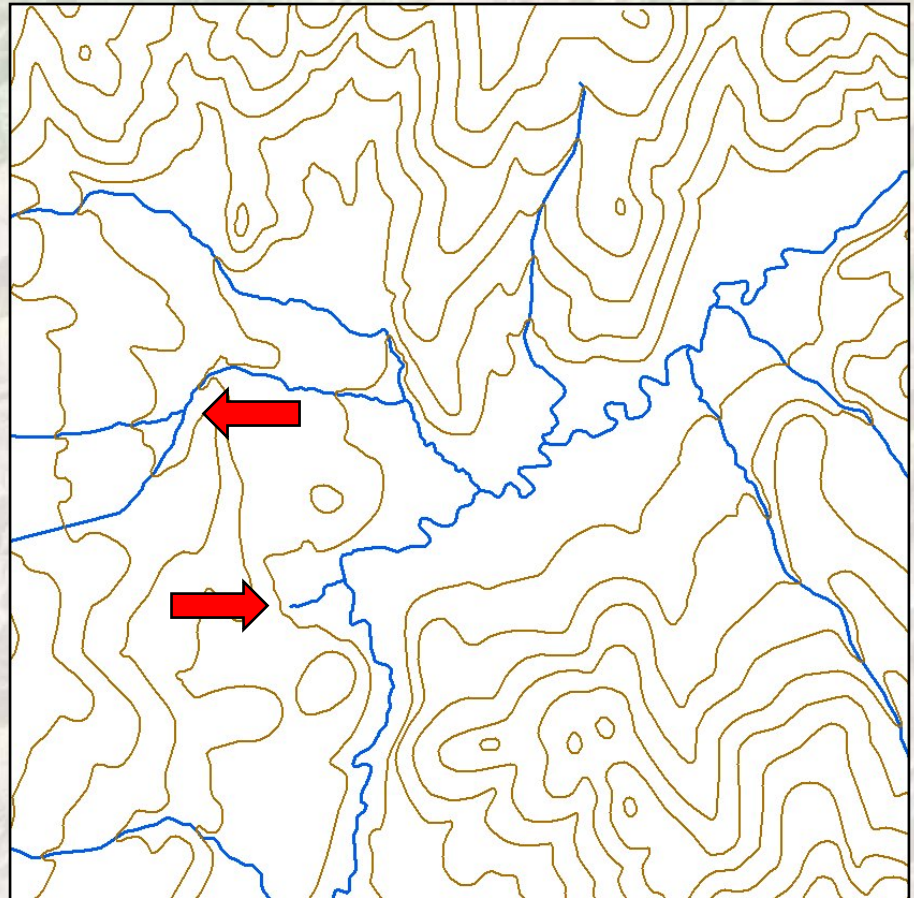


At stream
intersections

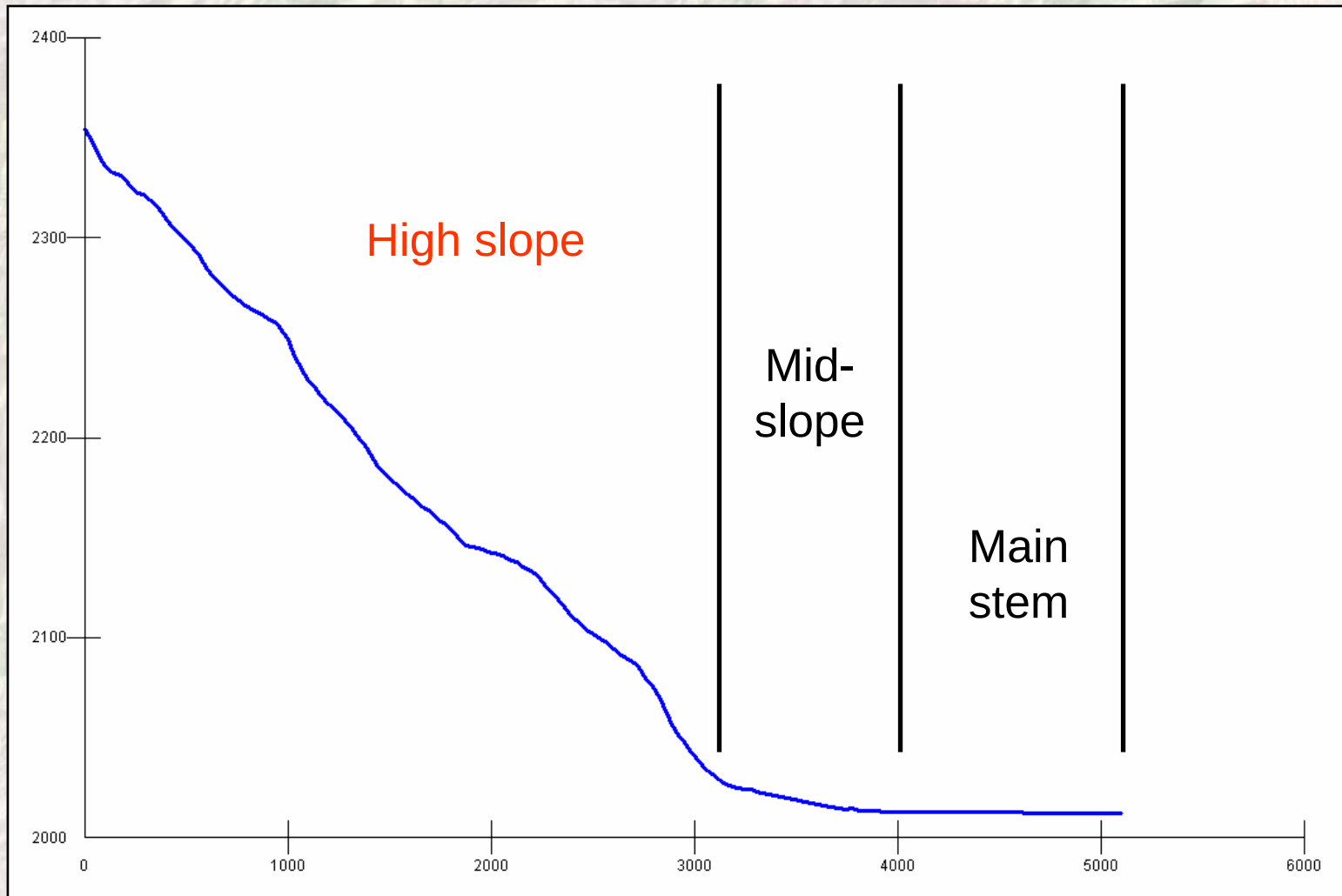
Equal interval

Why Not Use Contour Crossings for Entire Study Area?

- 1) Not available for the entire study area
- 2) Tag ends and stream intersections create technical problems

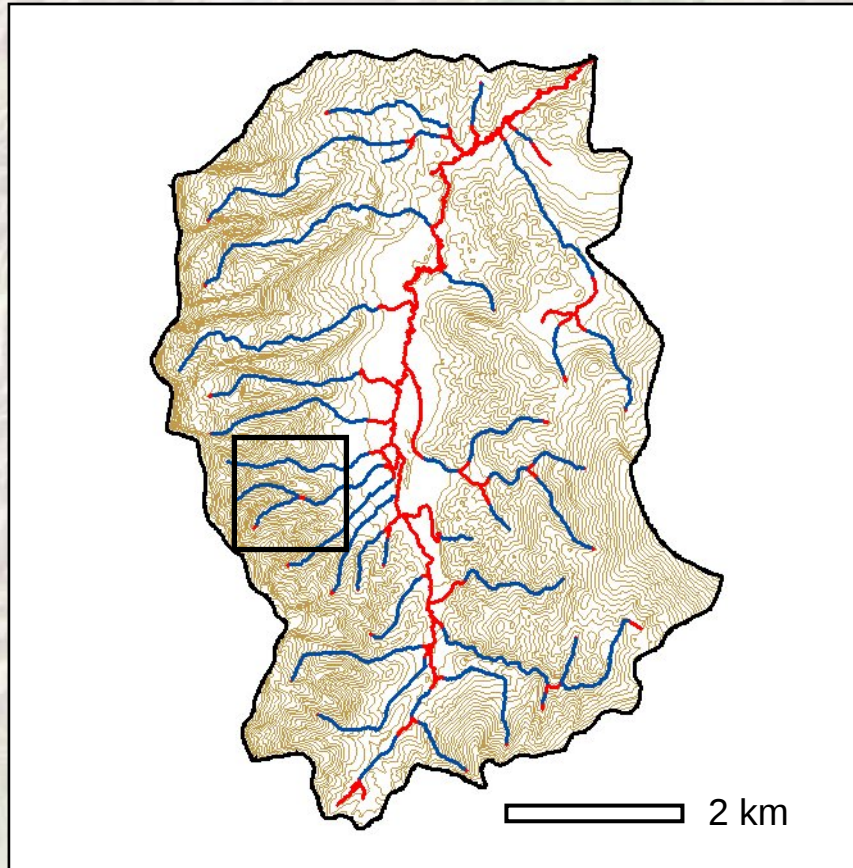


High Slope

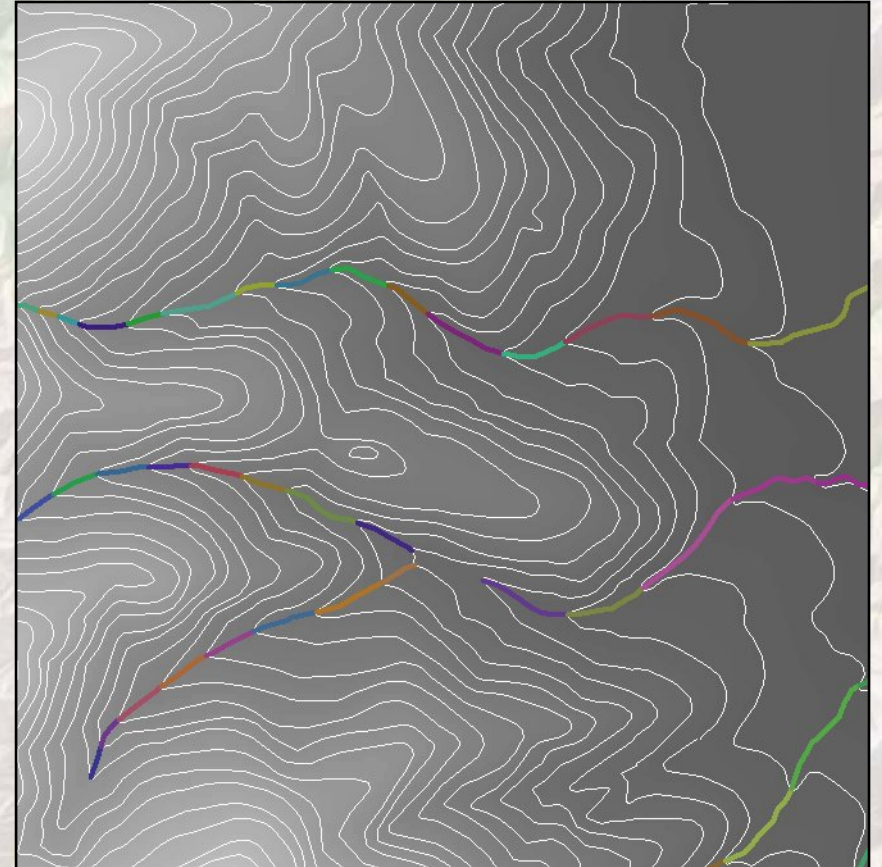


We'll use 100 m equal intervals

10 m DEM Accuracy in Higher Gradient Areas

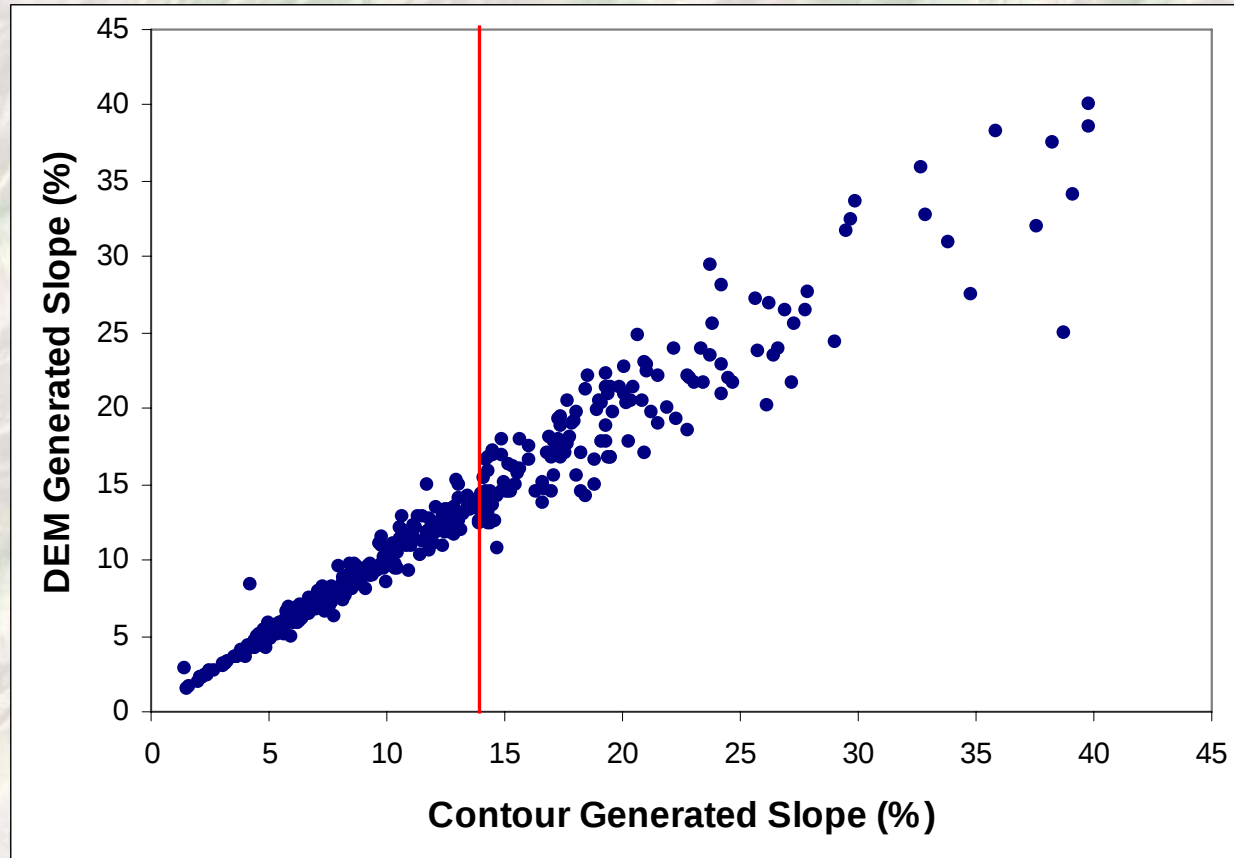


Blue = higher gradient streams



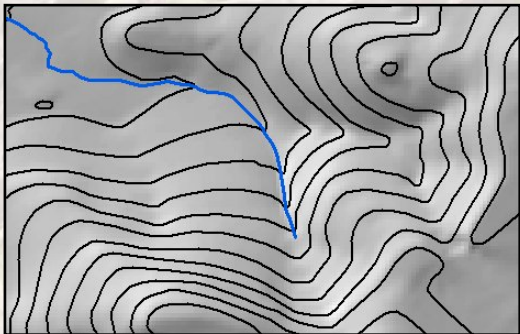
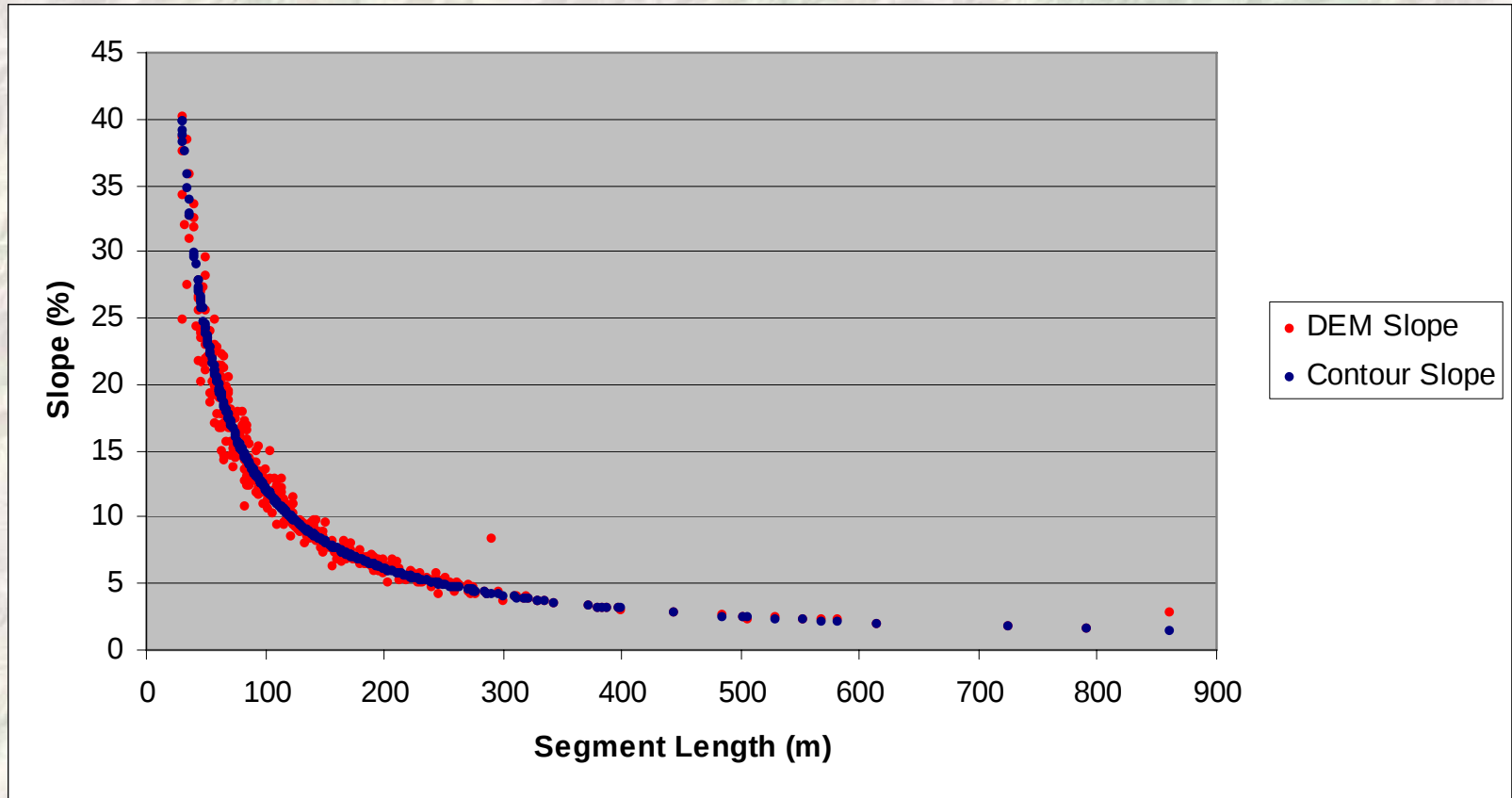
For comparison, compute slope using 1:24 k contours and DEM

Contour and DEM Generated Slope Comparison



Note divergence at higher slopes

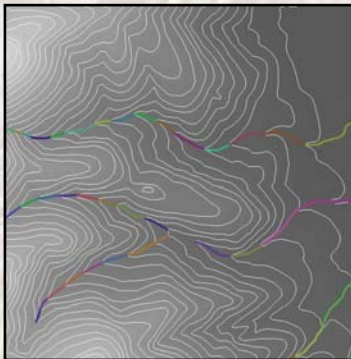
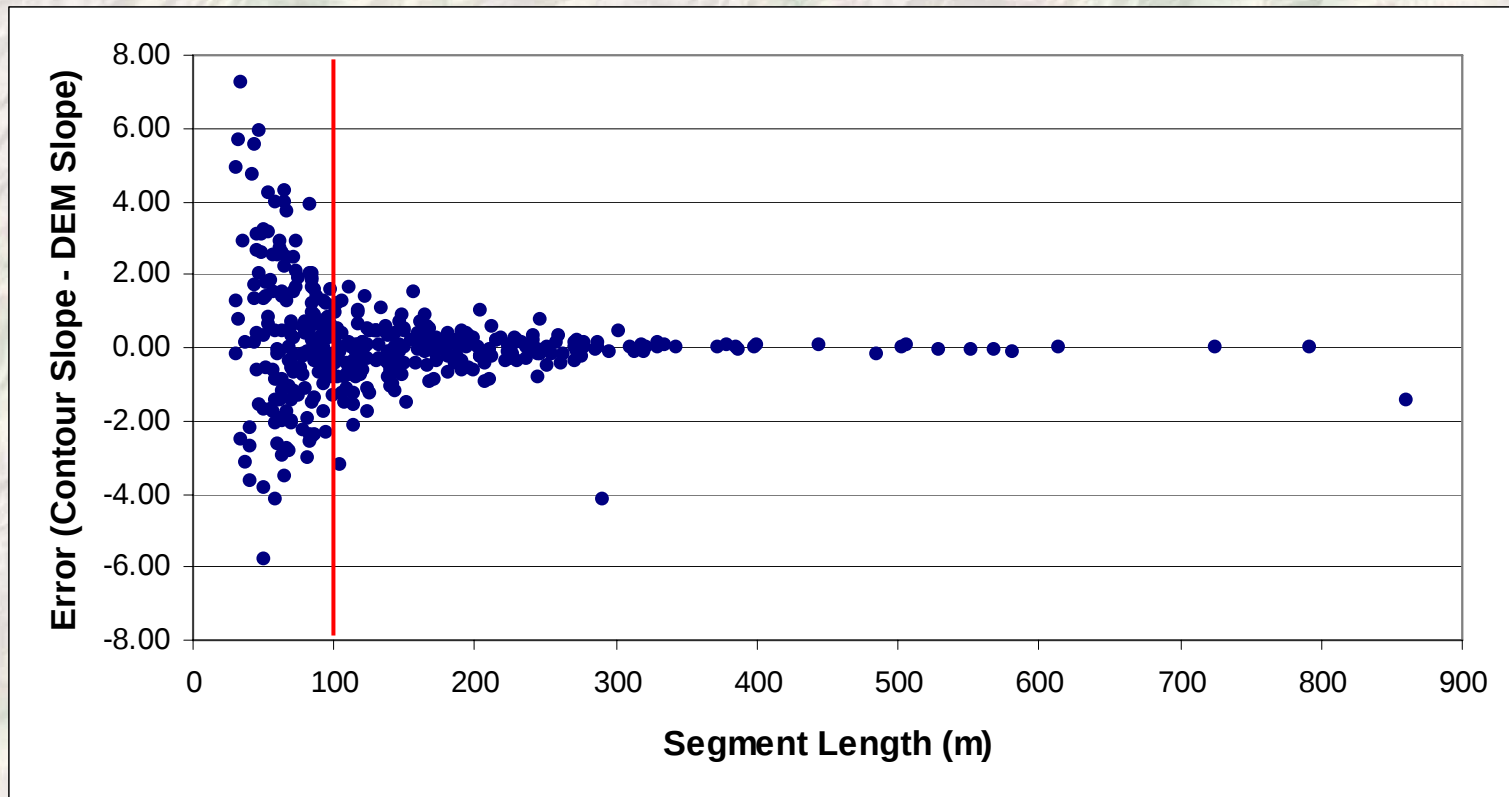
Slope and Segment Length



Contours get closer together at higher slopes and segment length decreases

Note error in DEM model

Errors vs. Stream Segment Length



Mean slope error for segment lengths:

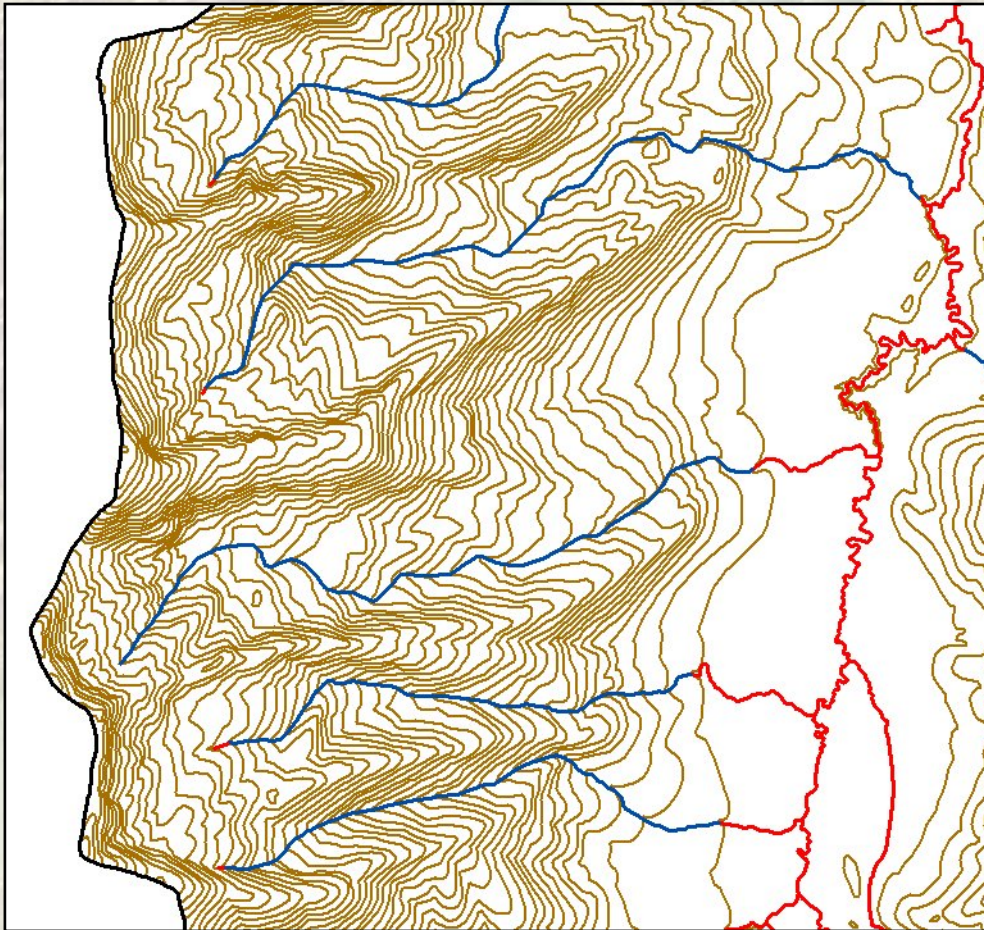
Greater than 100 m .42% pts

Equal to 100 m .68% pts

Less than 100 m 1.64% pts

Median Stream Segment Length

40' Contour Interval

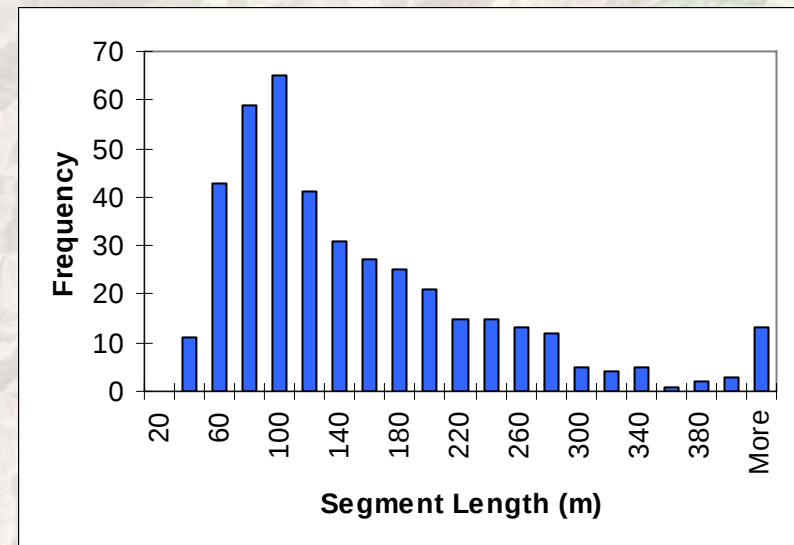


Segment length between contours

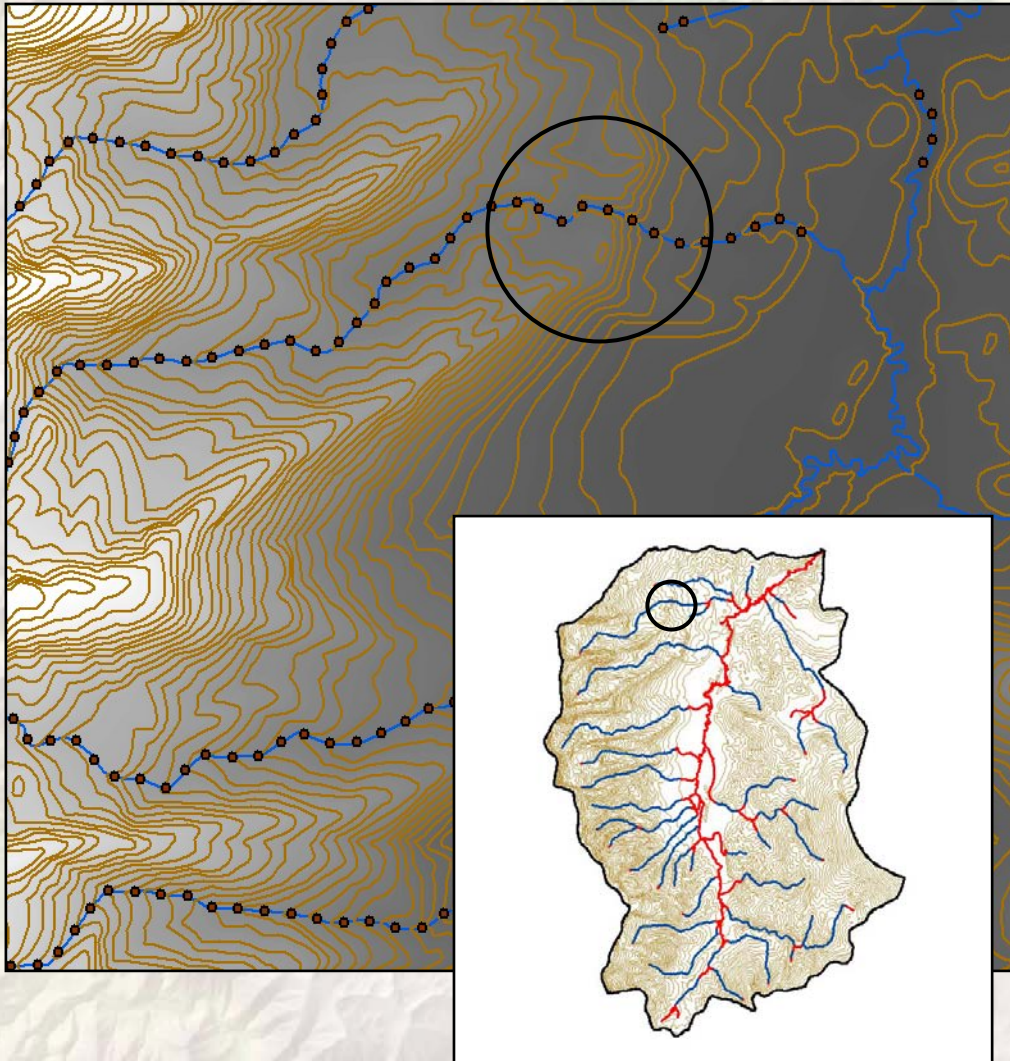
Mean = 147 m

Median = 114 m

n = 411



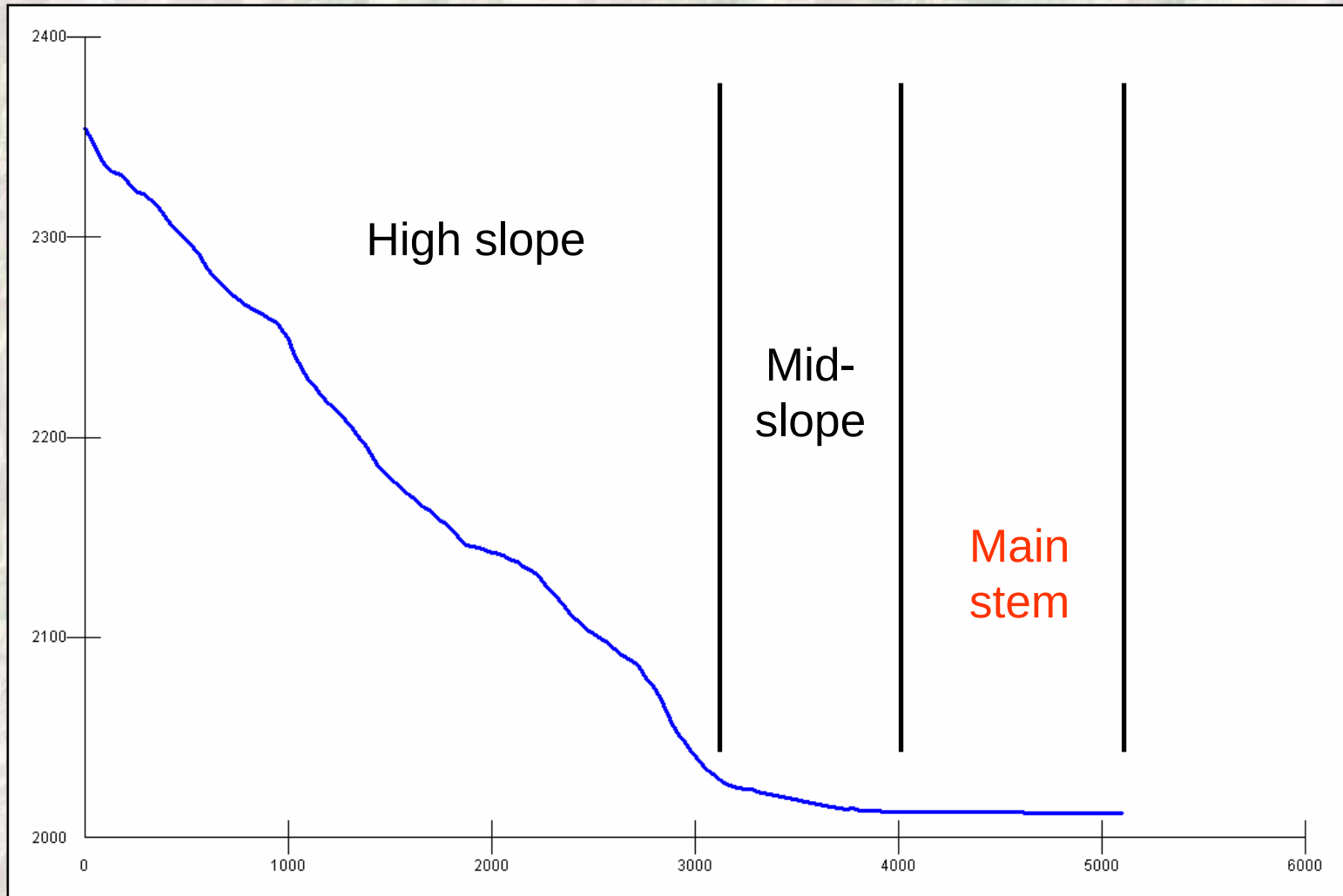
Gradient Calculation for Higher Slope Reaches – 100 m Spacing



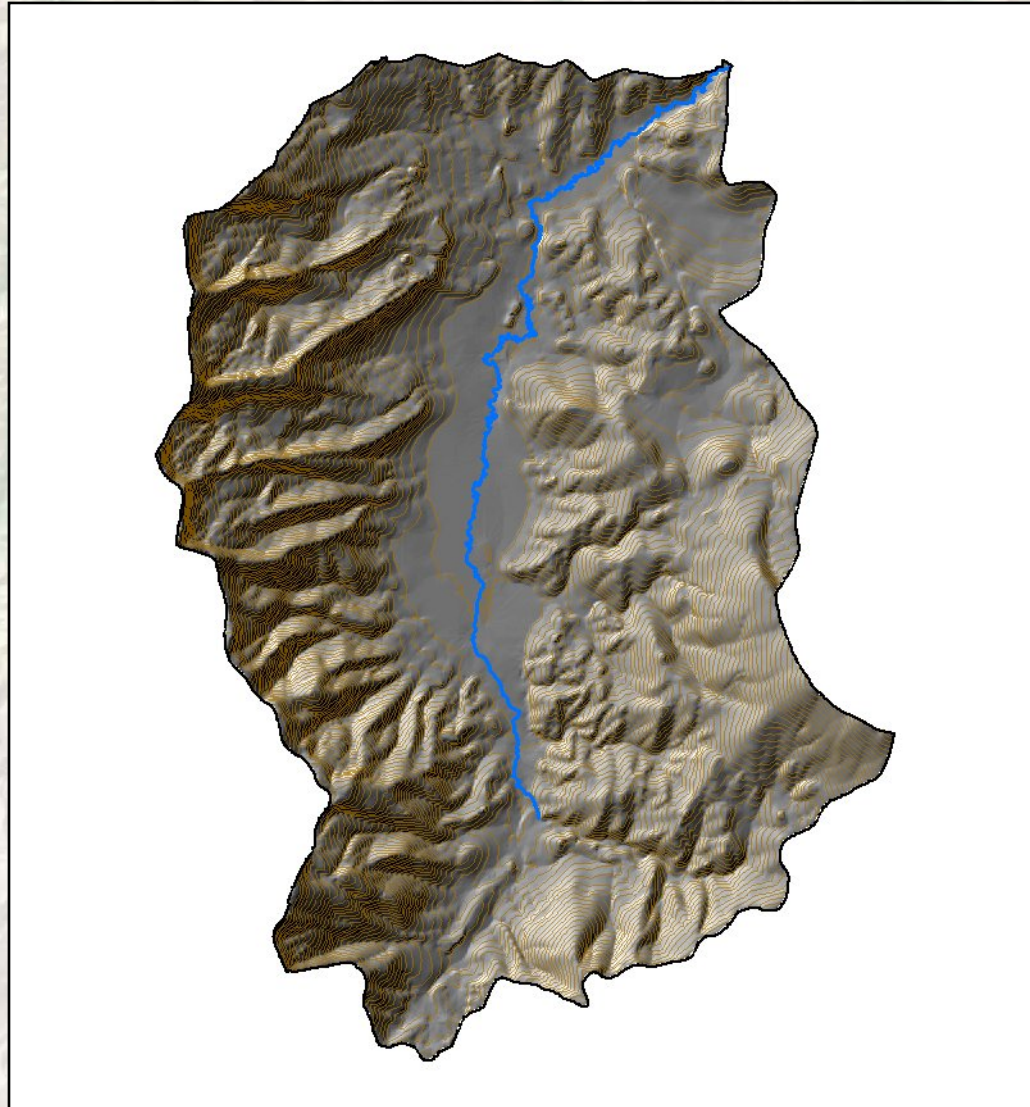
- 1) We used 100 m interval spacing along NHD lines with 10 m DEM.
- 2) Fine enough resolution to detect some natural barriers (slope > 20%)
- 3) Not so coarse that undesirable averaging occurs

Average error = 0.68% pts

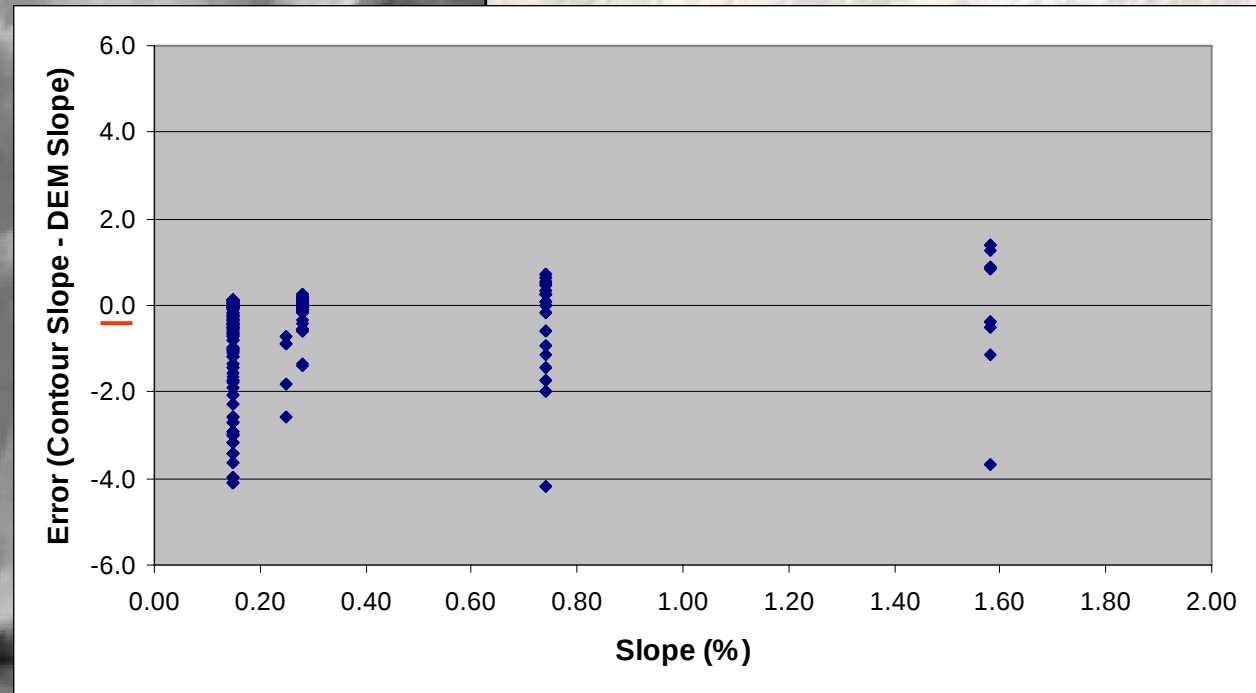
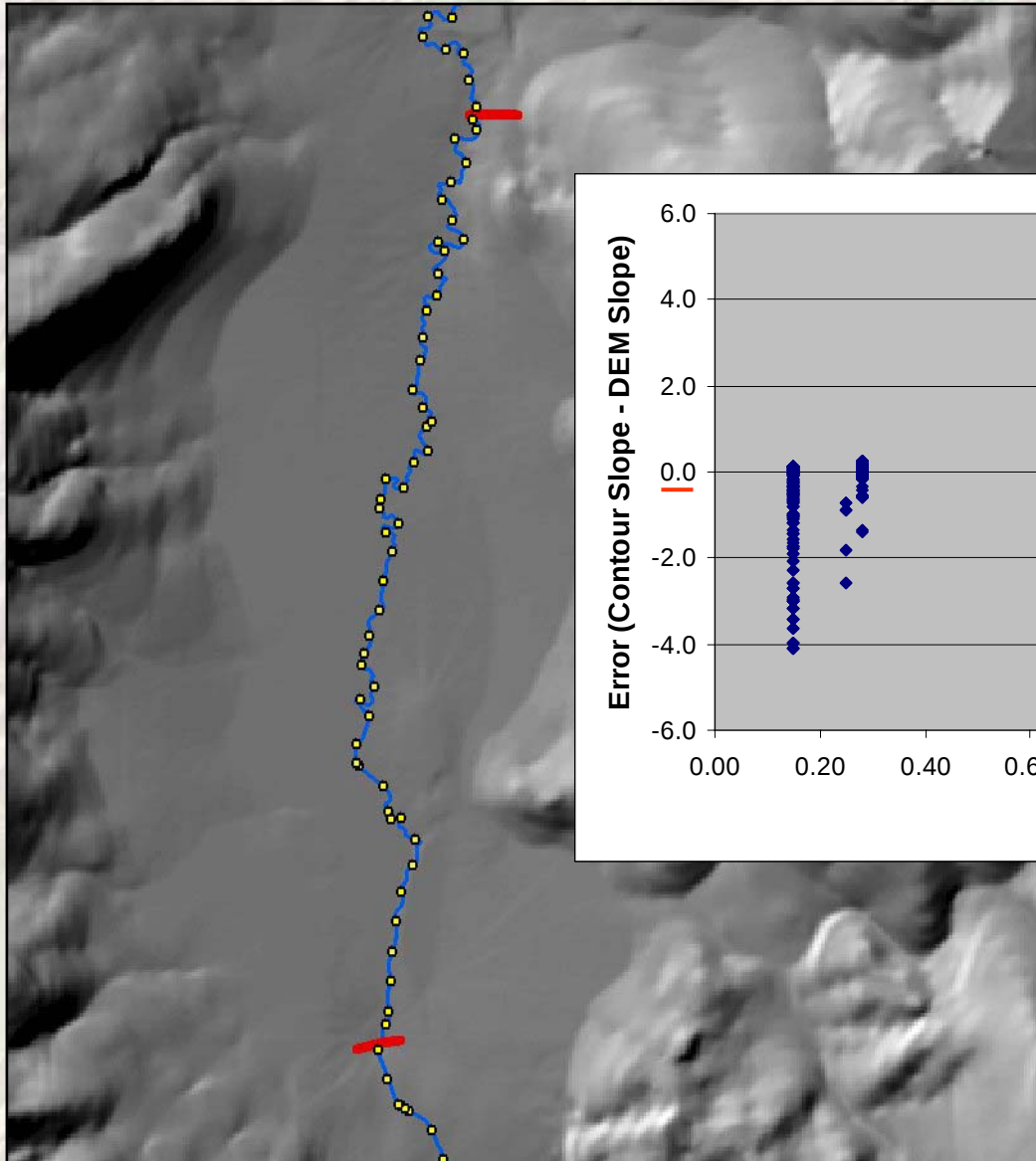
Main Stem



Gradient Calculation for Main Stem Reaches



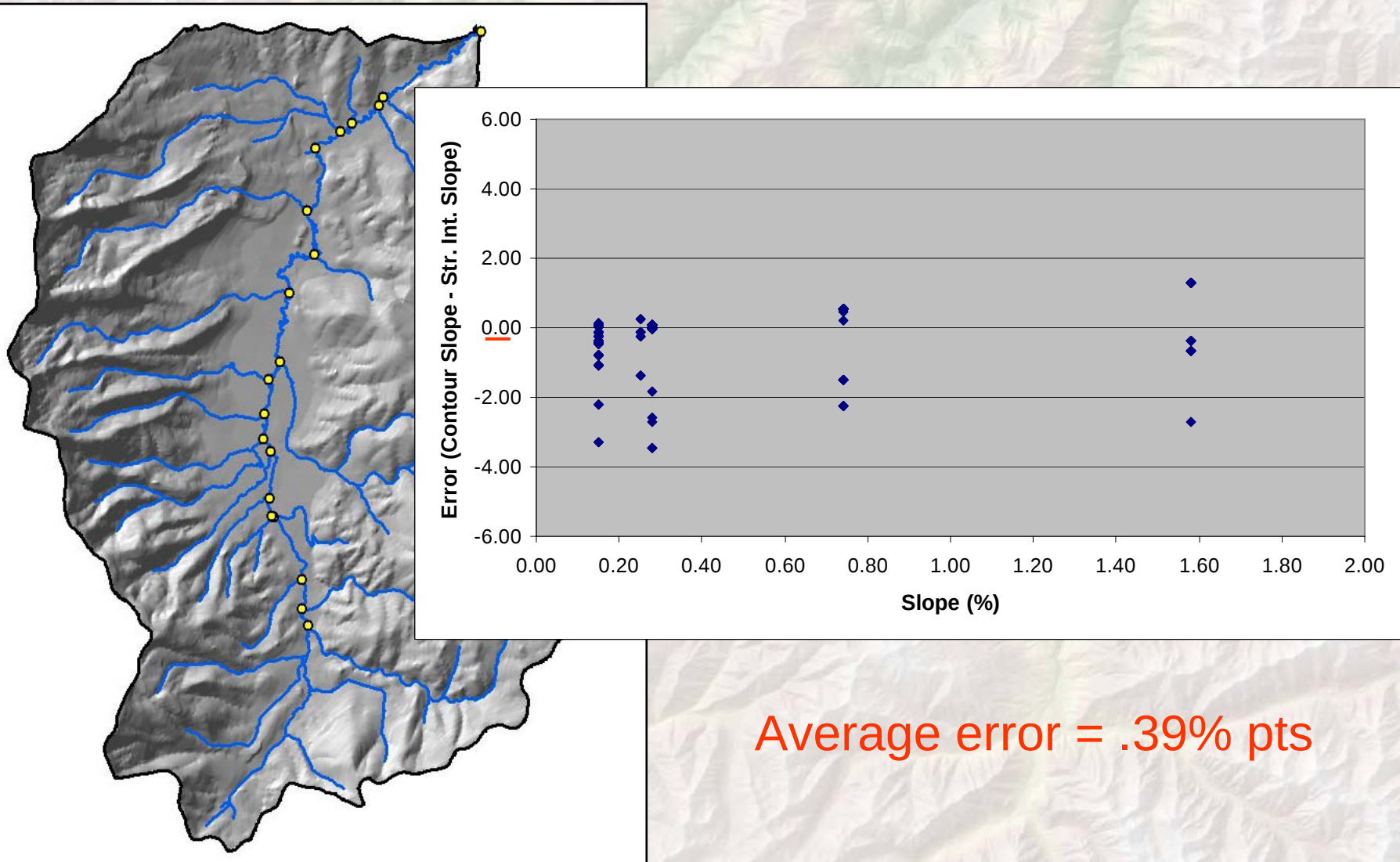
Contour Slope vs. 100 m Interval



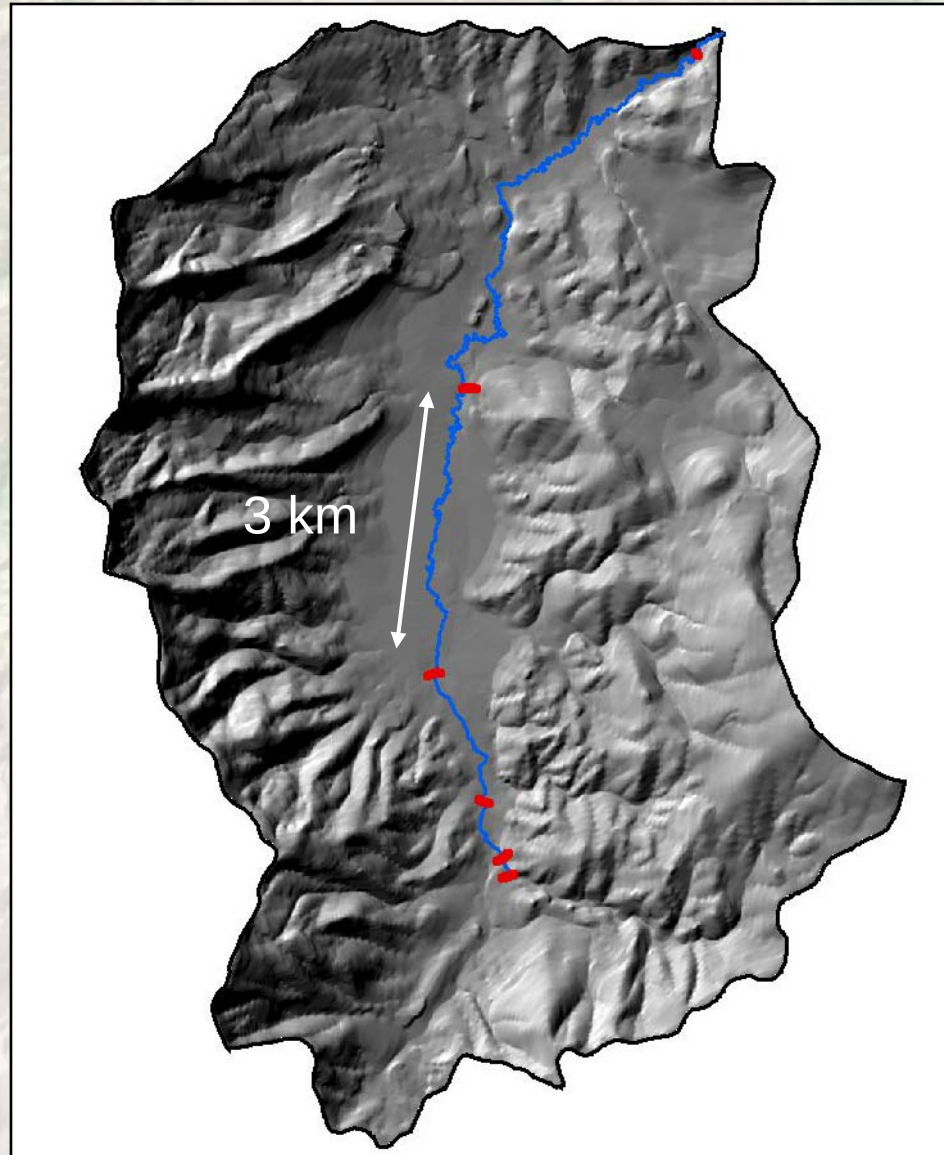
Average error = .75% pts

Gradient Calculation for Main Stem Reaches

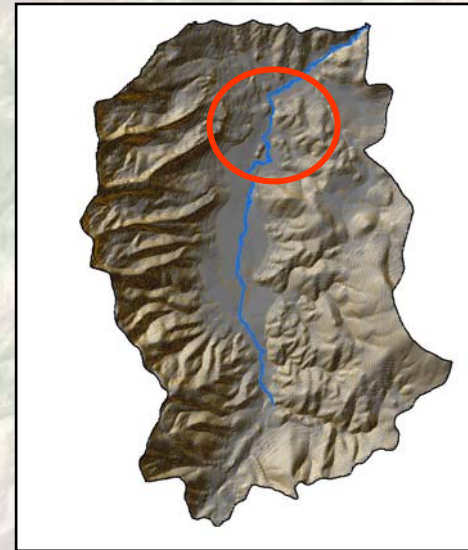
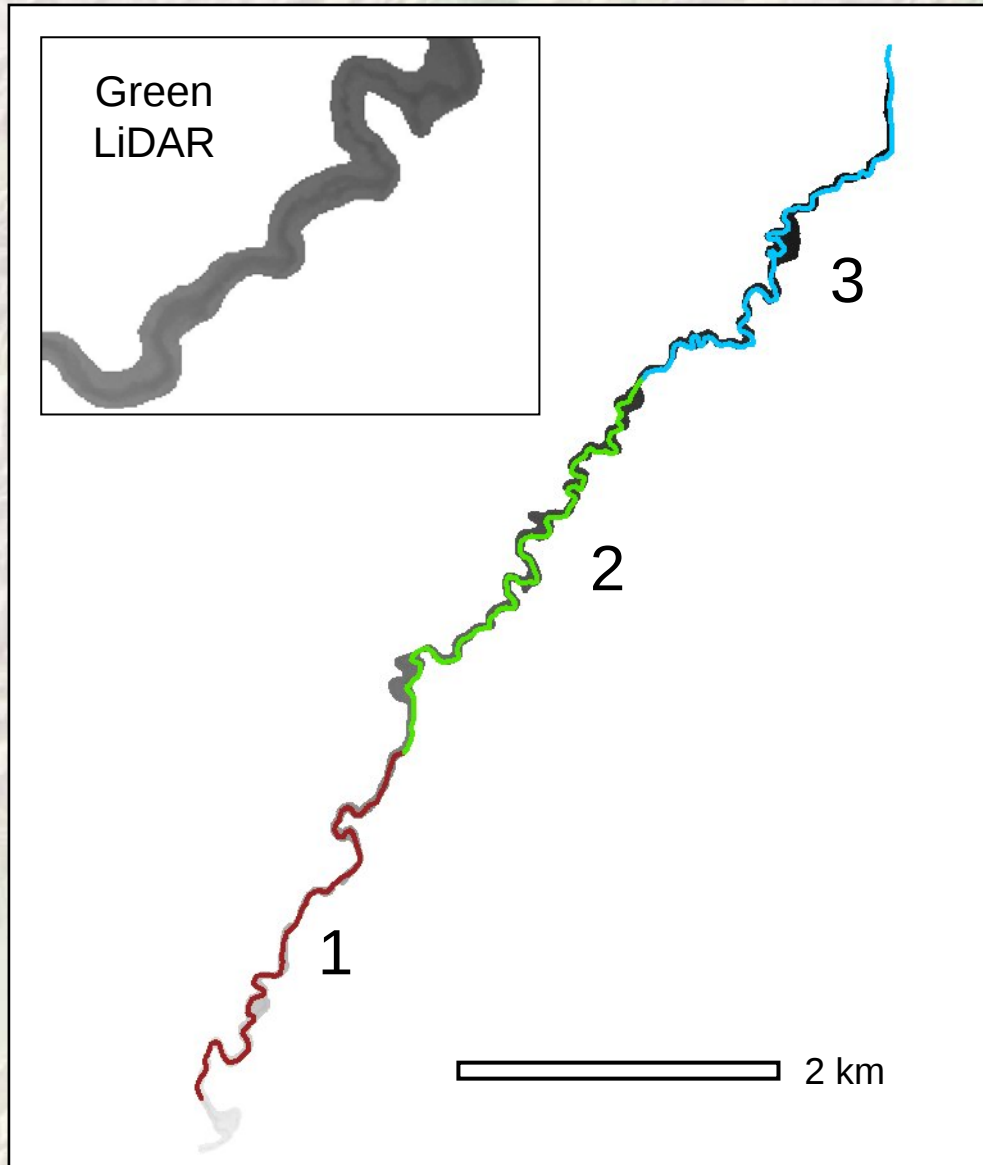
Stream Intersections



Gradient Calculation for Main Stem Reaches at Contour Crossings



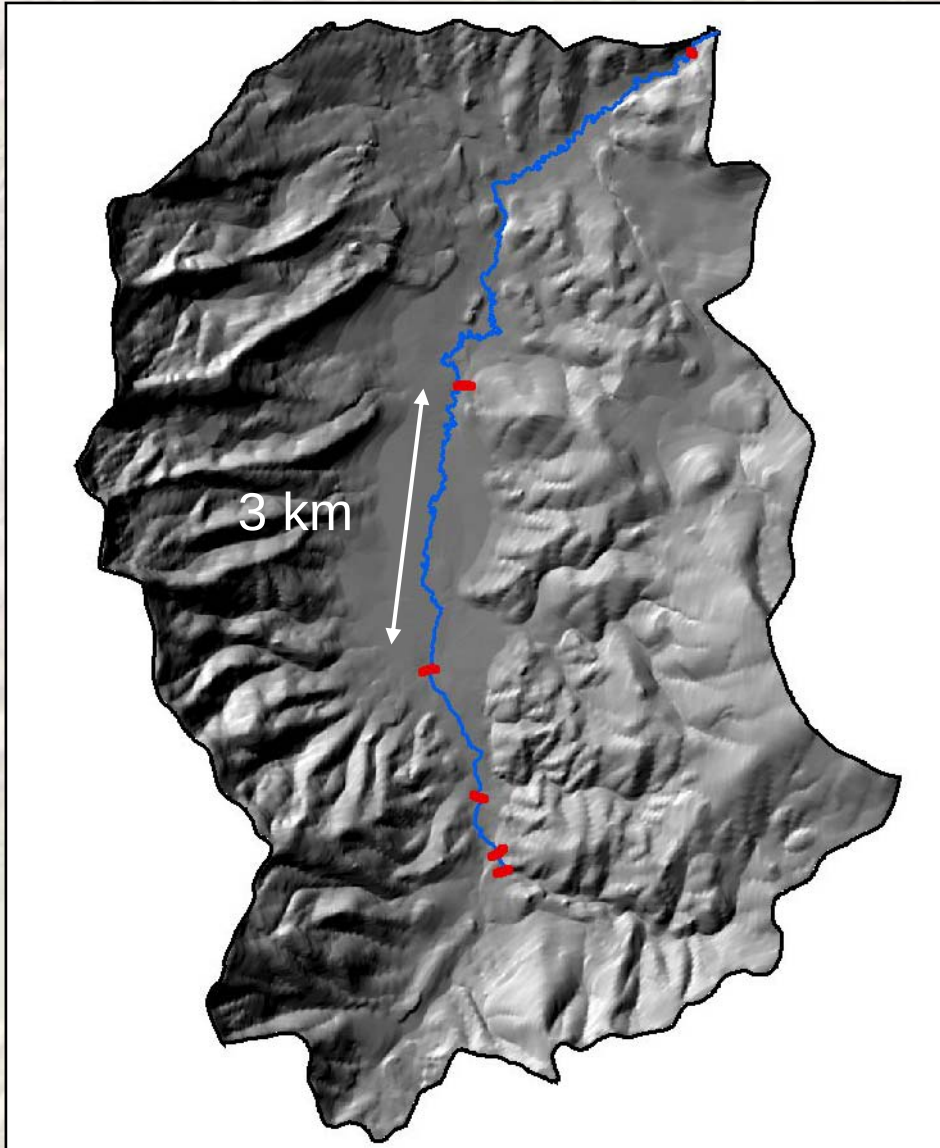
LiDAR vs. Contour Gradient Comparison



Segment No.	Contour Slope	LiDAR Slope
1	.41%	.45%
2	.35%	.35%
3	.36%	.32%

Average error = .03% pts

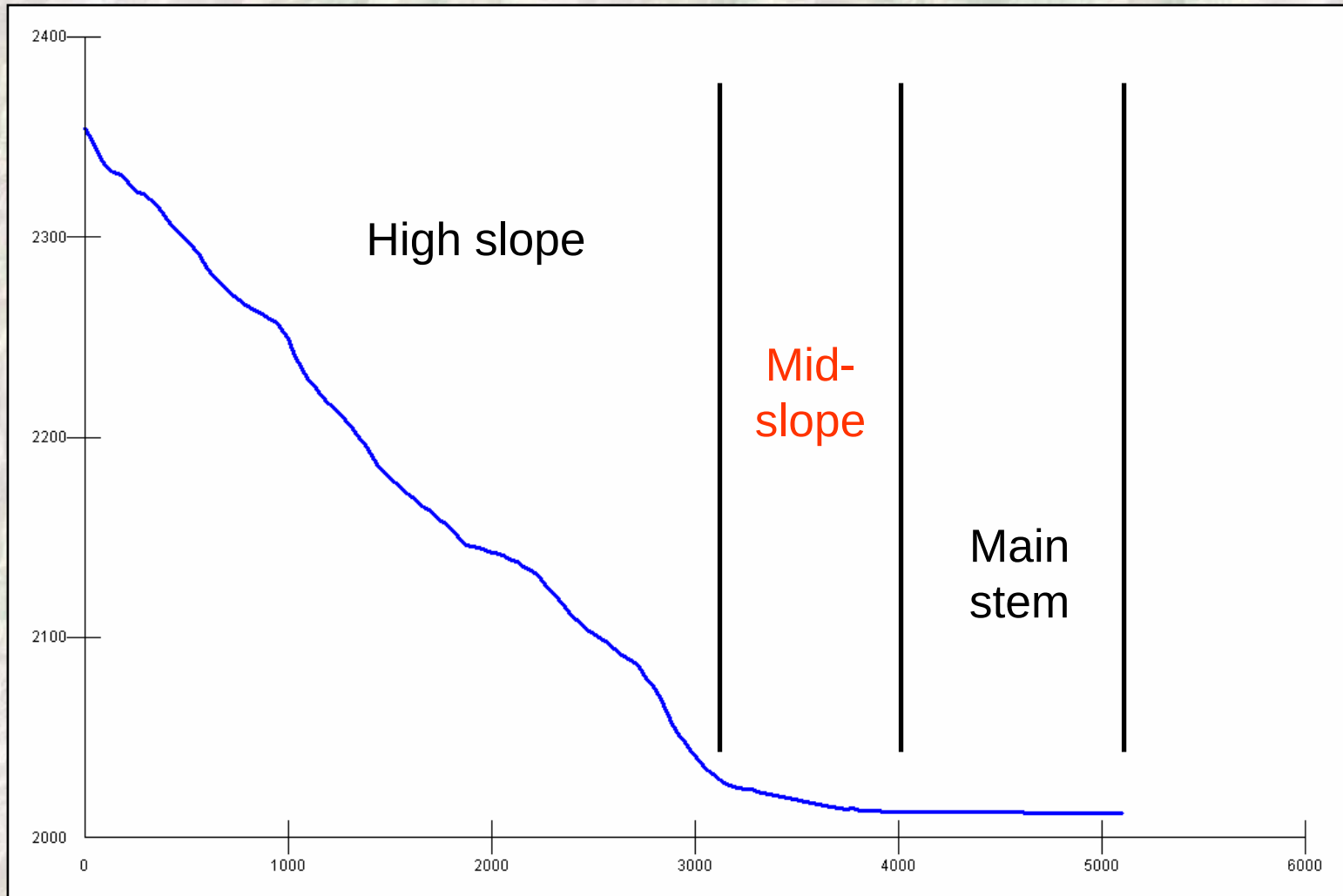
Gradient Calculation for Main Stem Reaches



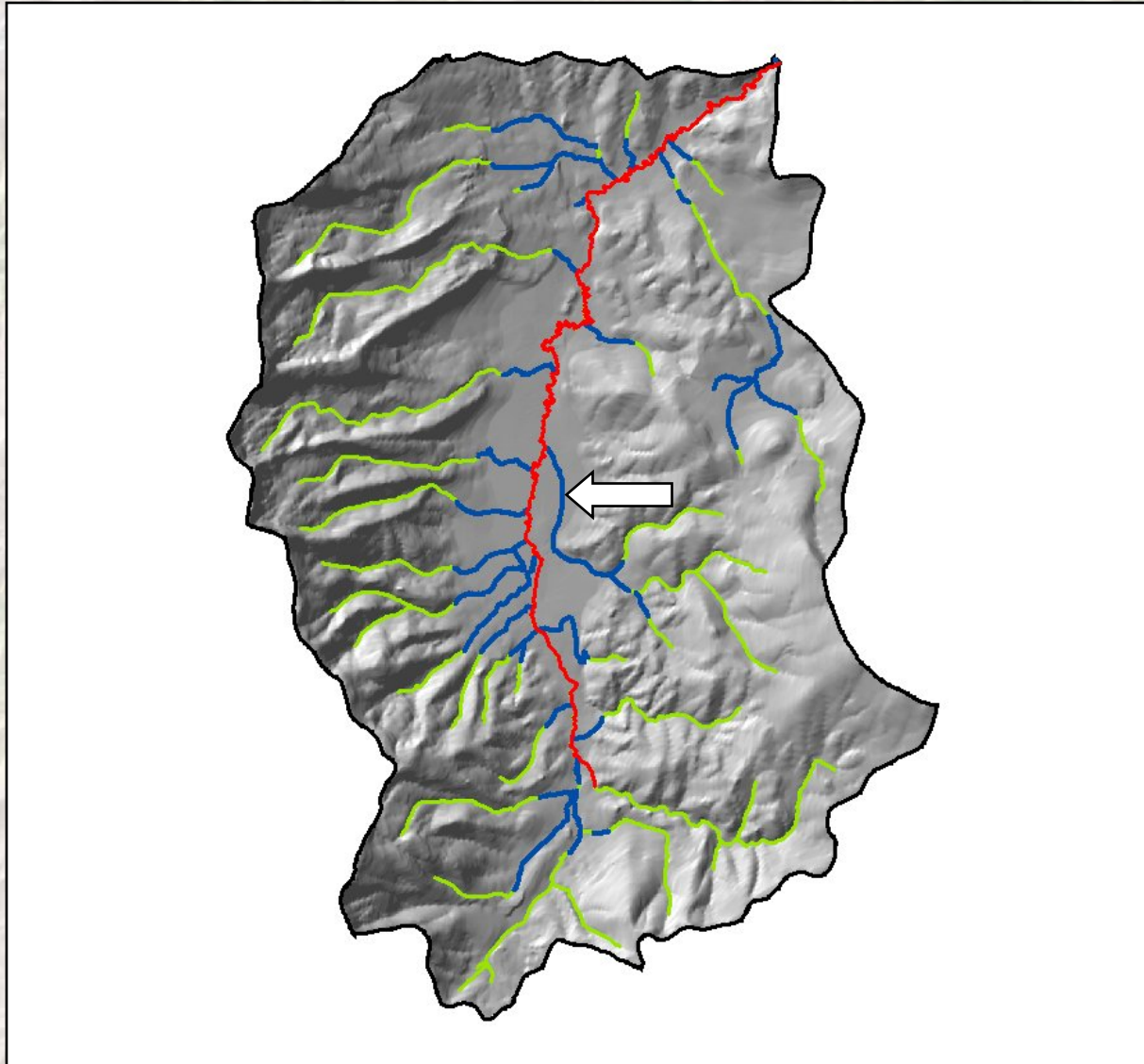
- We used quad contour crossings along main stem
- Contour crossings were digitized on-screen from DRGs

Average error = .03% pts

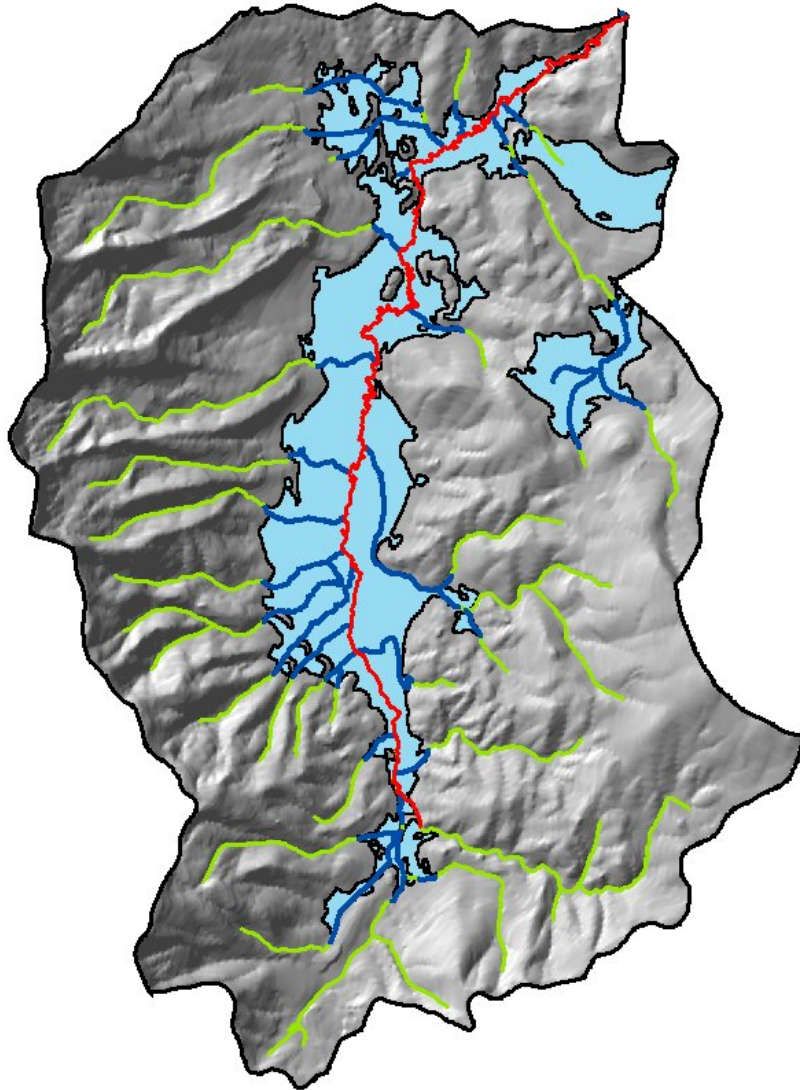
Mid-slope



Mid-slope Reaches



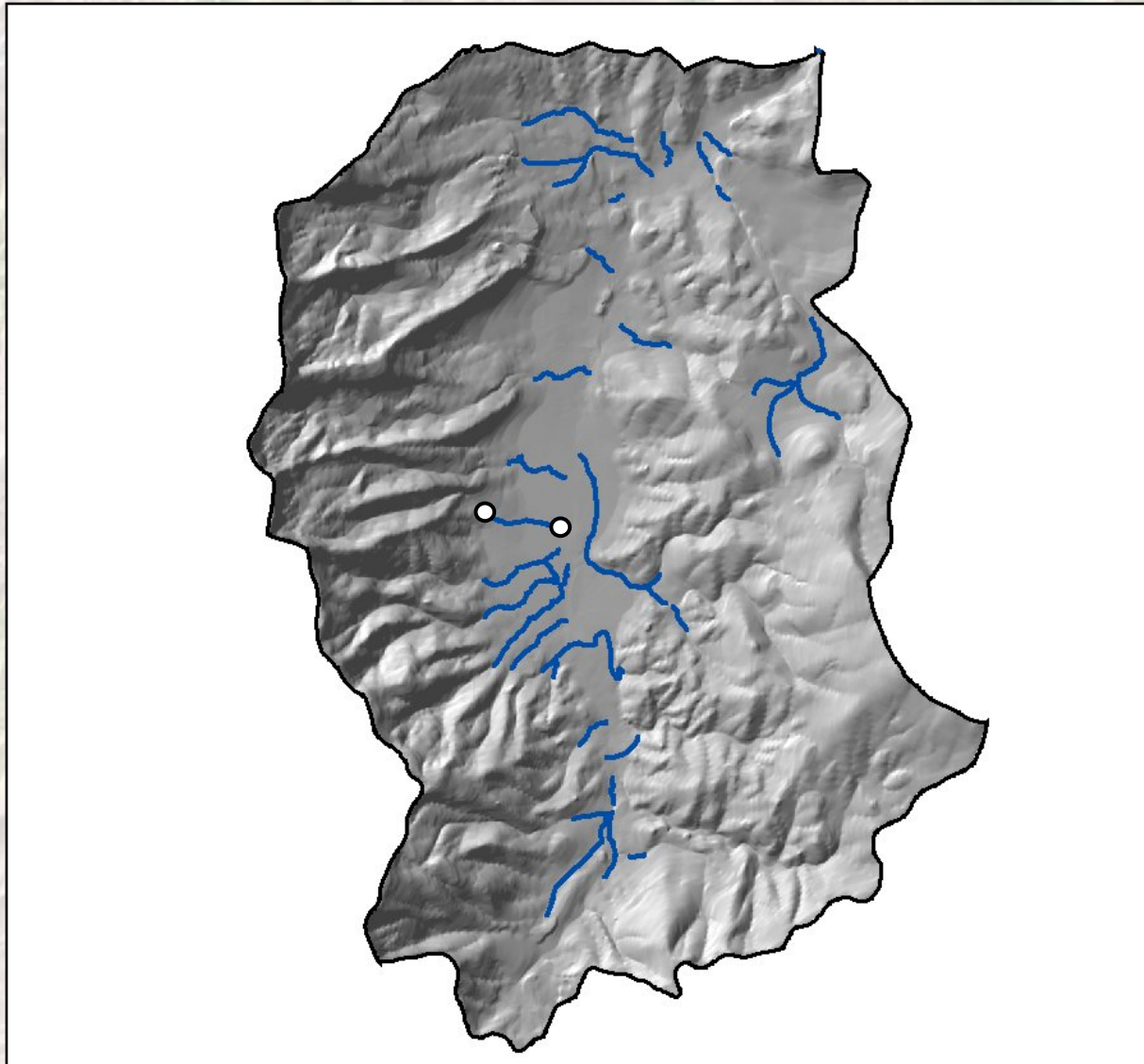
Mid-slope Reaches and Flat Valley Bottom Delineation



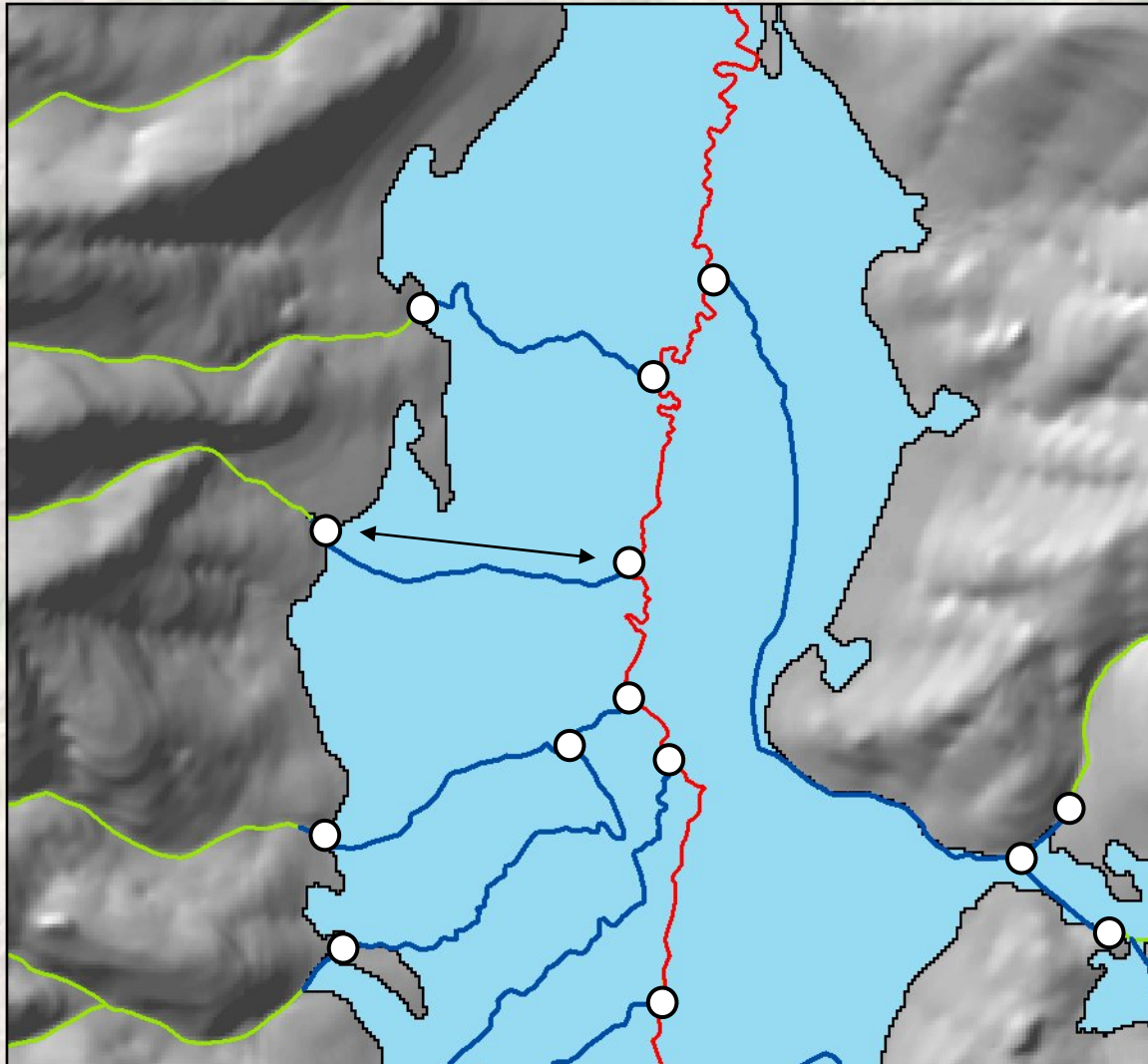
Procedure

- 1) Overlay valley bottom
- 2) Exclude main stem reaches

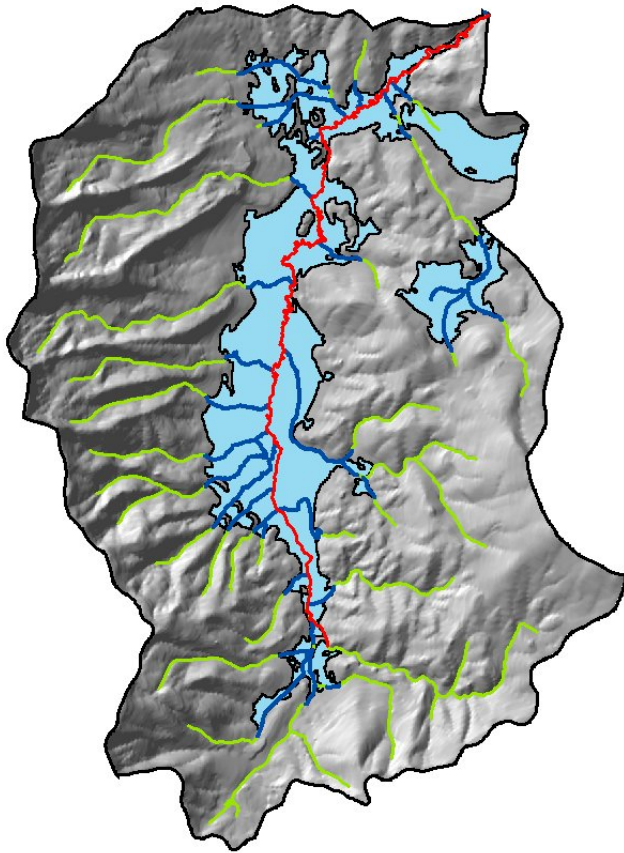
Mid-slope Reaches



Compute Slope Between Break Lines and Stream Intersections with 10 m DEM



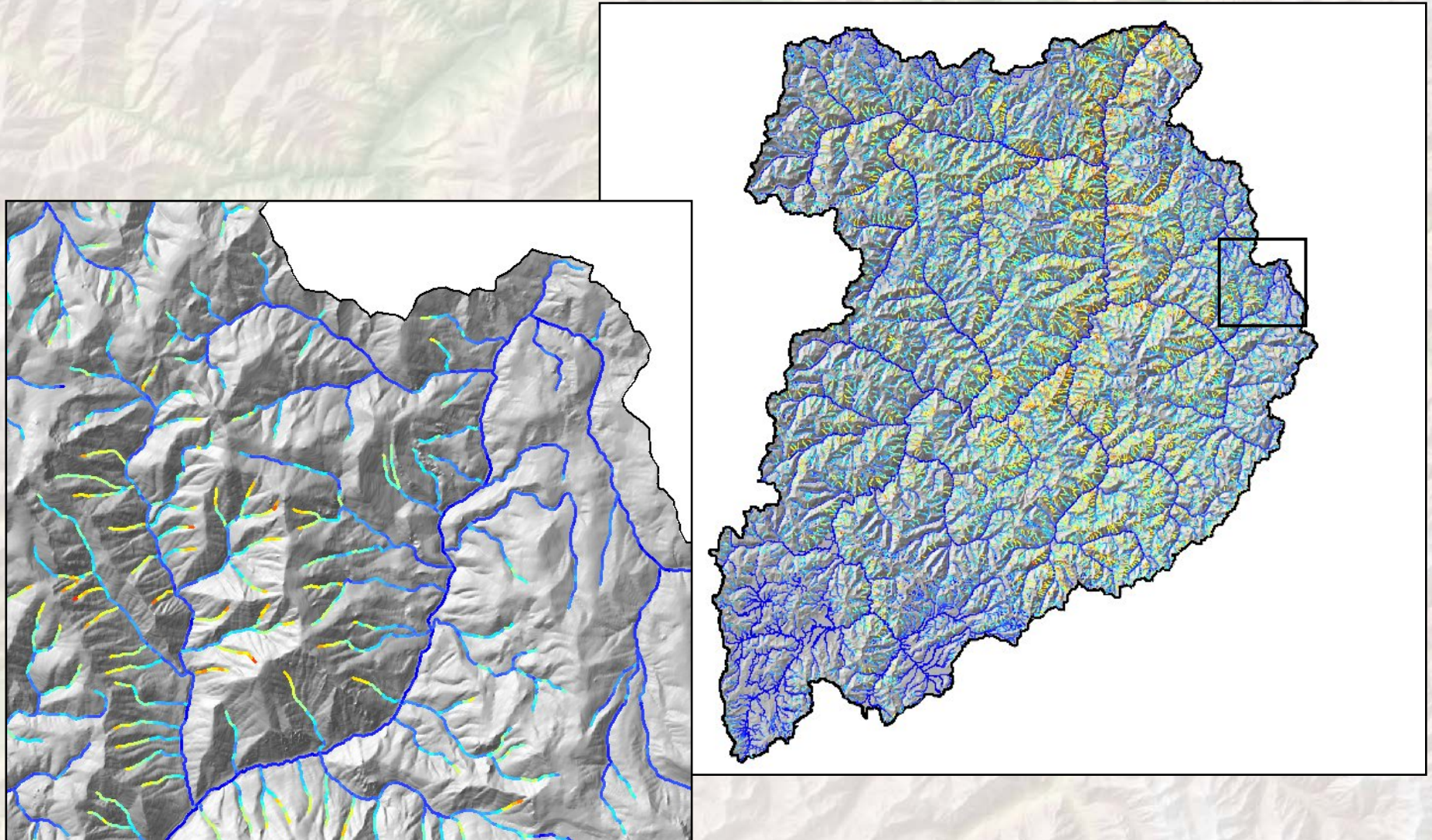
Gradient Calculation for Mid-slope Reaches



- 1) We used 10 m DEM elevations at valley bottom break lines and stream intersections
- 2) Output not validated against contours, but should be better than main stem results at intersections

Average error < .39% pts

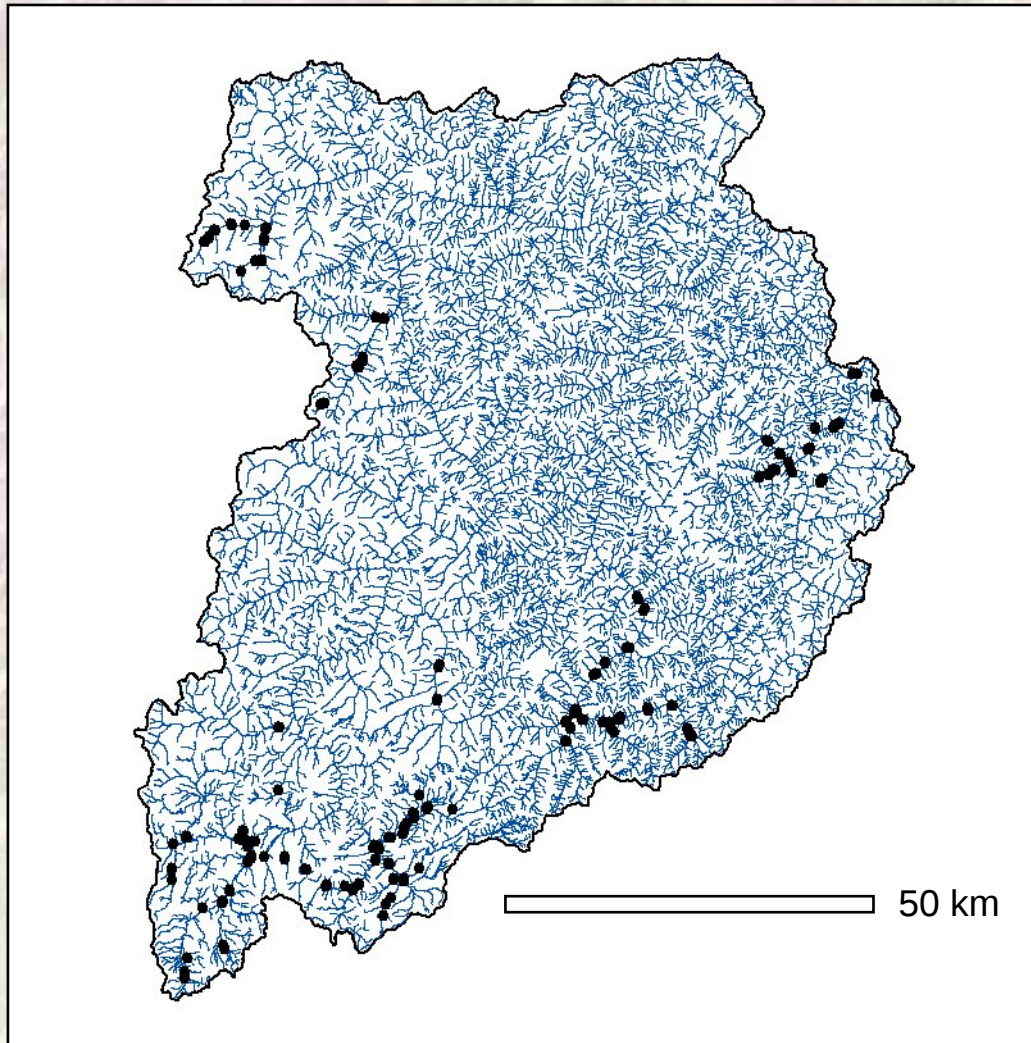
Final Stream Gradient Map



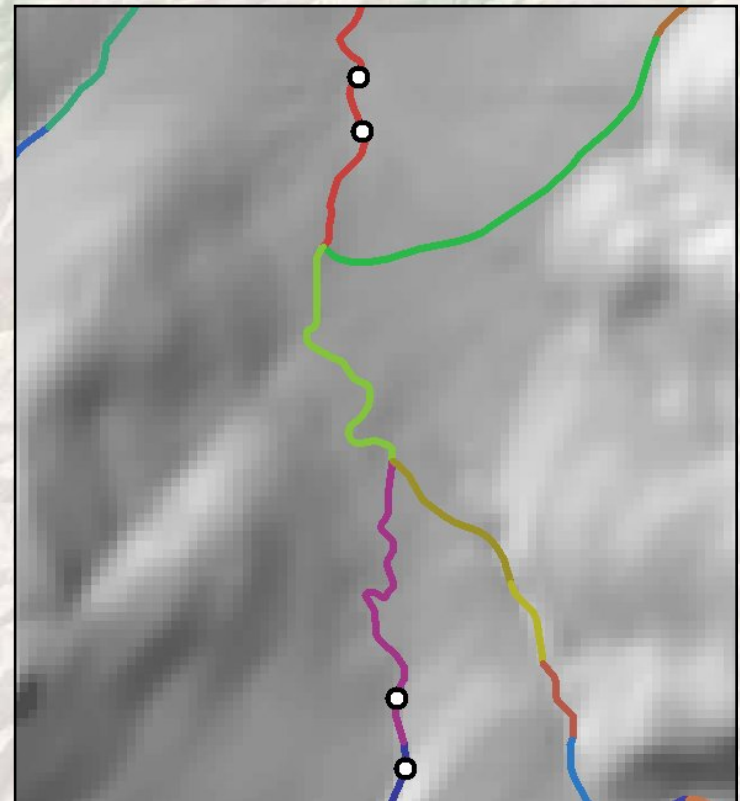


Field Data

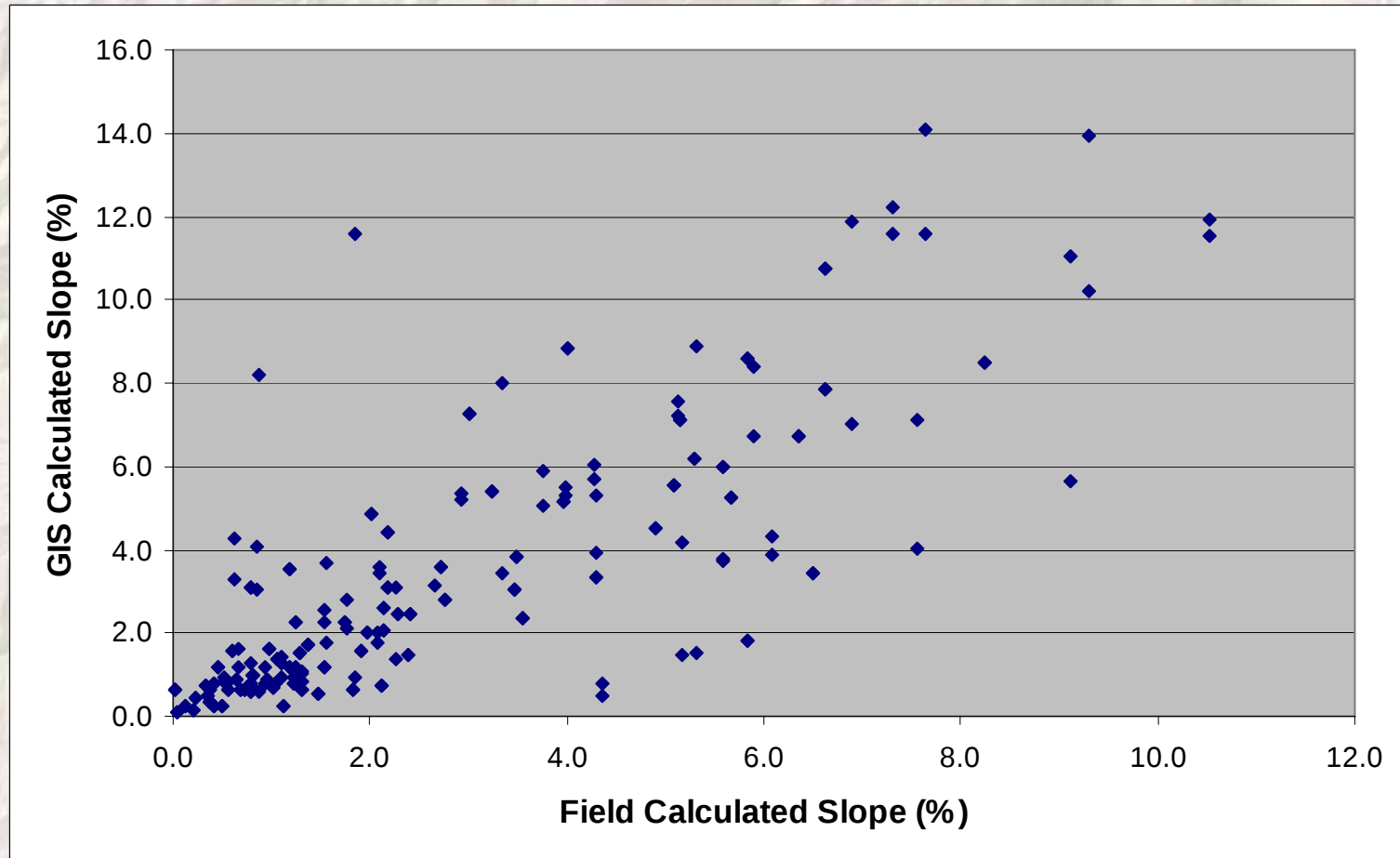
Field Calculated vs. GIS Calculated Gradient



$n = 238$



Field Calculated vs. GIS Calculated Gradient



Average error = 1.54% pts
R-squared = .67

Conclusions

- 1) The most appropriate interval spacing for measuring slope in higher gradient areas is about 100 m when using 10 m DEM data. **Average error ~ 0.68% pts.**
- 2) For main stem, low gradient channels, gradient is best computed between quad contour intervals. **Average error ~ 0.03% pts.**
- 3) At intermediate slopes, gradient can be computed between valley bottom break lines and stream intersections with 10 m DEM data. **Average error < 0.39% pts.**

Recommendation

10 m DEM data have variable accuracy
dependent on slope and landscape position

Fish and watershed models that
incorporate stream gradient should
account for these errors

Acknowledgements

RMRS – Boise Lab

John Buffington – Research Geomorphologist

Dan Isaak – Research Fisheries Biologist

Bruce Rieman – Research Fisheries Biologist

Russ Thurow – Research Fisheries Biologist

Sharon Parkes – GIS Specialist

Dona Horan – Fisheries Biologist

Jim McKean – Research Geomorphologist

Carolyn Bohn – Hydrologist

Bob Smith – Idaho Department of Lands